COMS21103: Linear Programming

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- Optimising a function is finding the *minimum* or *maximum* value of a function
- A linear function... e.g. 5 + 3x + 4y
- A linear inequality... e.g. $5x + 3y \le 10$, $3 + 5y \ge 4z$

Linear Programs arise in a variety of practical applications...

Example

A publisher has orders for 400 copies of a certain text from Bristol (b) and 600 copies from Leeds(I). The company has 700 copies in a warehouse in Birmingham (B) and 800 copies in a warehouse in London (L). It costs £5 to ship a text from Birmingham to Bristol, but it costs £4 to ship it to Leeds. It costs £10 to ship a text from London to Bristol, but it costs £8 to ship it from London to Leeds. How many copies should the company ship from each warehouse to Bristol and Leeds to fill the order at the least cost?

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 - cost

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- What do you want to optimise?
 - cost
 - minimise

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What is the linear function?

Example

- What is the linear function?
 - Define variables
 - x: # of items shipped from B to b
 - y: # of items shipped from L to b
 - w: # of items shipped from B to I
 - z: # of items shipped from L to I

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 - Define variables

x: # of items shipped from B to b

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•
$$f(x, y, w, z) = 5x + 10y + 4w + 8z$$

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Subject to what linear inequalities?

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 - Required shipments
 - $x + y \ge 400$ $w + z \ge 600$

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 - Required shipments
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 - Available Stock
 - $x + w \le 700$ y + z < 800

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- Subject to what linear inequalities?
 - Required shipments
 - $x + y \ge 400$
 - $w + z \ge 600$
 - Available Stock
 - $x + w \le 700$ y + z < 800
 - Non-negative Inequalities
 - $x \ge 0, y \ge 0, w \ge 0, z \ge 0$

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Linear Program - Non-standard form

minimise 5x + 10y + 4w + 8z *subject to* $x + y \ge 400$ $w + z \ge 600$ $x + w \le 700$ $y + z \le 800$ $x \ge 0, y \ge 0, w \ge 0, z \ge 0$

Linear Program - Matrix Representation

minimise5x + 10y + 4w + 8zsubject to $1x + 1y + 0w + 0z \ge 400$ $0x + 0y + 1w + 1z \ge 600$ $1x + 0y + 1w + 0z \le 700$ $0x + 1y + 0w + 1z \le 800$ $x \ge 0, y \ge 0, w \ge 0, z \ge 0$

Linear Program - Matrix Representation

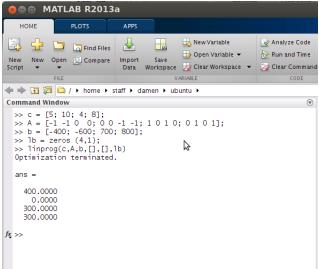
 $\begin{array}{lll} \mbox{minimise} & 5x+10y+4w+8z \\ \mbox{subject to} & -1x-1y+0w+0z \leq -400 \\ & 0x+0y-1w-1z \leq -600 \\ & 1x+0y+1w+0z \leq 700 \\ & 0x+1y+0w+1z \leq 800 \\ & x \geq 0, \ y \geq 0, \ w \geq 0, \ z \geq 0 \end{array}$

Linear Program - Matrix Representation

$$\mathbf{c} = \begin{bmatrix} 5\\10\\4\\8 \end{bmatrix}, \, \mathbf{A} = \begin{bmatrix} -1 & -1 & 0 & 0\\0 & 0 & -1 & -1\\1 & 0 & 1 & 0\\0 & 1 & 0 & 1 \end{bmatrix}, \, \mathbf{b} = \begin{bmatrix} -400\\-600\\700\\800 \end{bmatrix}, \, \mathbf{x} = \begin{bmatrix} x\\y\\w\\z \end{bmatrix}$$

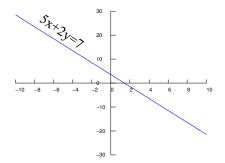
$$\begin{array}{ll} \mbox{minimise} & \mbox{c}^T \mbox{x} \\ \mbox{subject to} & \mbox{A} \mbox{x} \leq \mbox{b} \\ \mbox{x} \geq \mbox{0} \end{array}$$

Can be solved using a linear solver



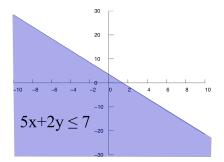
In two dimensions...

• A linear equation defines a line in space 5x + 2y = 7



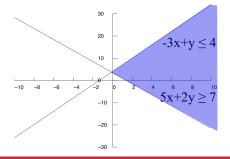
In two dimensions...

• A linear **inequality** defines a half-space $5x + 2y \le 7$

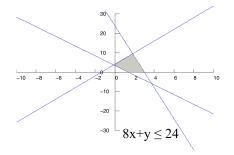


In two dimensions...

- Multiple linear inequalities constrain the space of solutions
- Setting the variables x and y to values that satisfy all constraints results in a feasible solution
- Setting the variables x and y to values that fail to satisfy any constraint results in an **infeasible** solution
- > The shaded area represents the space of feasible solutions



When the set of inequalities represent a convex hull in space, the feasible region is said to be **bounded**



In two dimensions...

If the linear program has no feasible solution, the linear program is said to be infeasible

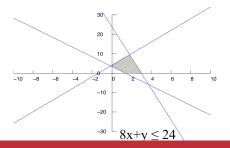
e.g. $5x + 2y \ge 7$ $x \le 0$ $y \le 0$

If a linear program has some feasible solutions but does not have a finite optimal objective value, it is said to be **unbounded**

For the linear program

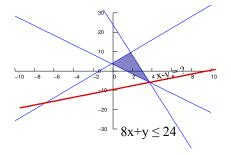
 $\begin{array}{ll} \mbox{minimise} & x-y\\ \mbox{subject to} & 5x+2y\geq 7\\ & -3x+y\leq 4\\ & 8x+y\leq 24\\ & x\geq 0, y\geq 0 \end{array}$

The search is for a feasible solution that minimises the objective function x - y



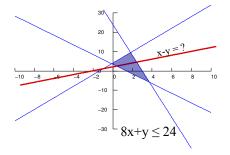
In two dimensions...

> The objective function takes different values within the feasible region



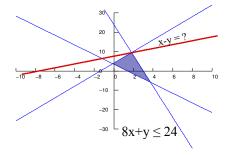
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Linear Programming

In two dimensions...

- It is no accident that the optimal solution to the linear program occurs at a vertex of the feasible solution.
- The optimal value must be at the boundary of the feasible region
- The intersection is thus either a single vertex or a line segment (that contains two vertices)
- Eureka... calculate the objective function at all vertices!

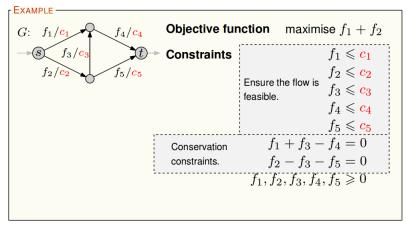
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- It is no accident that the optimal solution to the linear program occurs at a vertex of the feasible solution.
- The optimal value must be at the boundary of the feasible region
- The intersection is thus either a single vertex or a line segment (that contains two vertices)
- Eureka... calculate the objective function at all vertices!
- But... we cannot easily graph linear programs in 3+ dimensions

Max-Flow as a Linear Program

Max-flow problem can be formulated as a linear program



- Takes as input a linear program and returns an optimal solution
- It starts at some vertex and performs a sequence of iterations
- In each iteration, it moves along an edge to a neighbouring vertex whose objective value is smaller than the current vertex
- Terminates when it reaches a local optimum
- As the vertex is a convex hull, the local optimum is actually a global optimum

The standard form to solve a simplex algorithm is:

maximise
$$\sum_{j=1}^{n} c_j x_j$$

subject to $\sum_{j=1}^{n} a_{ij} x_j \le b_i$ for $i = 1, 2, ...m$
 $x_j \ge 0$ for $j = 1, 2, ...n$

A linear function is in non-standard form for the Simplex algorithm if

- The objective function is a minimisation rather than a maximisation
- There might be variables without nonnegativity constraints
- There might be equality rather than inequality constraints
- There might be inequality constraints with an opposite sign

To convert to a standard form:

If the objective function is a minimisation → negate the coefficients e.g.

minimise -2x + 3y

becomes

maximise 2x - 3y

To convert to a standard form:

If a variable y does not have a non-negativity constraint → change y to y₁ - y₂ and add y₁ ≥ 0, y₂ ≥ 0 e.g.

$$\begin{array}{c|cccc} \text{maximise} & 2x - 3y \\ \text{subject to} & x + y \leq 7 \\ & x - y \leq 4 \\ & x \geq 0 \end{array} \rightarrow \begin{array}{c|ccccc} \text{maximise} & 2x - 3y_1 + 3y_2 \\ \text{subject to} & x + y_1 - y_2 \leq 7 \\ & x - y_1 + y_2 \leq 4 \\ & x, y_1, y_2 \geq 0 \end{array}$$

To convert to a standard form:

If equality constraint exists → replace by two inequalities ≤ b and ≥ b e.g.

 $\begin{array}{c|ccc} \text{maximise} & 2x - 3y \\ \text{subject to} & x + y = 7 \\ & & \\ & & \\ & & \\ \end{array} \rightarrow \begin{array}{c|cccc} \text{maximise} & 2x - 3y \\ \text{subject to} & x + y \leq 7 \\ & & x + y \geq 7 \\ & & \\ & & \\ \end{array}$

To convert to a standard form:

 \blacktriangleright If inequality constraint needs to change sign \rightarrow negate e.g.

$$\begin{array}{c|ccc} \text{maximise} & 2x - 3y \\ \text{subject to} & x + y \geq 7 \\ & & & \\ & & & \\ \end{array} \rightarrow \begin{array}{c|ccc} \text{maximise} & 2x - 3y \\ \text{subject to} & -x - y \leq -7 \\ & & & \\ & & & \\ \end{array}$$

e.g. convert the following linear program into standard form:

minimise subject to	$\begin{array}{l} 2x_1 + 7x_2 + x_3 \\ x_1 - x_3 = 7 \\ 3x_1 + x_2 \geq 24 \\ x_2 \geq 0 \\ x_3 \leq 0 \end{array}$
------------------------	---

After being in the standard form, the Simplex algorithm puts the linear program in the slack form.

$$z = \sum_{j=1}^{n} c_{j} x_{j}$$

$$x_{n+i} = b_{i} - \sum_{j=1}^{n} a_{ij} x_{j} \text{ for } i = 1, 2, ..., m$$

$$x_{i} \ge 0 \text{ for } i = 1, 2, ..., n + m$$

• For each inequality
$$\sum_{j=1}^{n} a_{ij} x_j \le b_i$$

Introduce a new variable s (called the slack variable because it measures the difference between the left and the right hand sides of the equation.)

• Rewrite the inequality
$$s = b_i - \sum_{j=1}^n a_{ij}x_j$$

Add a non-negativity constraint s ≥ 0

e.g. convert the following linear program from standard form to slack form:

$$\begin{array}{ll} \mbox{maximise} & 2x_1 - 3x_2 + 3x_3 \\ \mbox{subject to} & x_1 + x_2 - x_3 \leq 7 \\ & -x_1 - x_2 + x_3 \leq -7 \\ & x_1 - 2x_2 + 2x_3 \leq 4 \\ & x_1, x_2, x_3 \geq 0 \end{array}$$

- Step 1: add the slack variables
- Step 2: Replace the objective function value by z

$$\begin{array}{rll} z=&2x_1-3x_2+3x_3\\ x_4=&7-x_1-x_2+x_3\\ x_5=&-7-+x_1+x_2-x_3\\ x_6=&4-x_1+2x_2-2x_3\\ &x_1,x_2,x_3,x_4,x_5,x_6\geq 0 \end{array}$$

- Step 1: add the slack variables
- Step 2: Replace the objective function value by z

$$\begin{array}{rcl} z=&2x_1-3x_2+3x_3\\ x_4=&7-x_1-x_2+x_3\\ x_5=&-7-+x_1+x_2-x_3\\ x_6=&4-x_1+2x_2-2x_3\\ &x_1,x_2,x_3,x_4,x_5,x_6\geq 0 \end{array}$$

The variables on the left hand size of equalities are called **basic** variables

The variables on the right hand size of equalities are called nonbasic variables

The Simplex Algorithm - Basic Solution

- A feasible solution can be found by setting all nonbasic variables (right-hand side variables) to 0
- This is a feasible solution and is a vertex in the convex hull because of the non-negativity constraint.
- ▶ For the example below, **x** = (0, 0, 0, 30, 24, 36) and *z* = 0
- This is referred to as a basic feasible solution

- At each iteration in the simplex algorithm, we select a non-basic variable x_i
- This chosen variable should have a positive coefficient in the objective function
- So that increasing its value would increase the objective function
- Let's choose x₁

We try to increase x₁ as much as possible without increasing any non-negativity constraint

Ζ	=			3 <i>x</i> 1	+	<i>x</i> ₂	+	2 <i>x</i> ₃	(1)
<i>x</i> ₄	=								(2)
<i>x</i> ₅	=	24	-	2 <i>x</i> ₁	-	2 <i>x</i> ₂	-	5 <i>x</i> 3	(3)
<i>x</i> ₆	=	36	-	4 <i>x</i> ₁	-	<i>X</i> ₂	-	2 <i>x</i> ₃	(4)

- We try to increase x₁ as much as possible without increasing any non-negativity constraint
 - In (2), x₁ could be set to 30 max
 - In (3), x₁ could be set to 12 max
 - In (4), x_1 could be set to 9 max

_	=			3 <i>x</i> 1	+	<i>x</i> ₂	+	2 <i>x</i> ₃	(1)
<i>x</i> ₄	=	30	-	<i>x</i> ₁	-	<i>x</i> ₂	-	3 <i>x</i> 3	(2)
<i>x</i> 5	=	24	-	2 <i>x</i> ₁	-	2 <i>x</i> ₂	-	5 <i>x</i> ₃	(3)
<i>x</i> ₆	=	36	-	4 <i>x</i> ₁	-	<i>X</i> ₂	-	2 <i>x</i> ₃	(4)

- We try to increase x₁ as much as possible without increasing any non-negativity constraint
 - In (2), x₁ could be set to 30 max
 - In (3), x₁ could be set to 12 max
 - In (4), x₁ could be set to 9 max
- Equation (4) is the tightest constraint
- We therefore switch the roles of x₁ and x₆

Z	=			3 <i>x</i> 1	+	<i>x</i> ₂	+	2 <i>x</i> ₃	(1)
<i>X</i> ₄	=	30	-	<i>x</i> ₁	-	<i>x</i> ₂	-	3 <i>x</i> 3	(2)
<i>X</i> 5	=	24	-	2 <i>x</i> ₁	-	2 <i>x</i> ₂	-	5 <i>x</i> ₃	(3)
<i>x</i> ₆	=	36	-	4 <i>x</i> ₁	-	<i>x</i> ₂	-	2 <i>x</i> ₃	(4)

• We re-arrange (4) so
$$x_1 = 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4}$$

• We re-arrange (4) so
$$x_1 = 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4}$$

x₁ will be replaced by x₆ on the right-hand side of Equations 1-3

z	=		+	$3(9-\frac{x_2}{4}-\frac{x_3}{2}-\frac{x_6}{4})$	+	<i>x</i> ₂	+	2 <i>x</i> ₃	(1)
<i>x</i> ₄	=	30	-	$\left(9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4}\right)$	-	<i>x</i> ₂	-	3 <i>x</i> 3	(2)
<i>x</i> 5	=	24	-	$2(9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4})$	-	$2x_2$	-	5 <i>x</i> 3	(3)
<i>x</i> ₁	=	9	-	$\begin{array}{c} 3(9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4}) \\ (9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4}) \\ 2(9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4}) \\ \frac{x_2}{4} \end{array}$	-	$\frac{x_3}{2}$	-	$\frac{x_{6}}{4}$	(4)

Z	=	27	+	$\frac{x_2}{4}$	+	<u>x₃</u> 2	-	$\frac{3x_6}{4}$	(1)
<i>x</i> ₁	=	9	-	<u>x₂</u> 4	-	<u>x₃</u> 2	-	$\frac{x_6}{4}$	(2)
									(3)
<i>x</i> 5	=	6	-	$\frac{3x_2}{2}$	-	4 <i>x</i> ₃	+	<u>x₆</u> 2	(4)

• After this operation the basic variables become $(x_1, x_4 \text{ and } x_5)$

z	=	27	+	$\frac{x_2}{4}$	+	<u>x₃</u> 2	-	$\frac{3x_6}{4}$	(1)
<i>x</i> ₁	=	9	-	$\frac{x_2}{4}$	-	<u>x₃</u> 2	-	<u>x₆</u> 4	(2)
<i>x</i> ₄	=	21	-	$\frac{3x_2}{4}$	-	<u>5x3</u> 2	+	$\frac{x_6}{4}$	 (1) (2) (3) (4)
x 5	=	6	-	<u>3x2</u> 2	-	4 <i>x</i> ₃	+	<u>x₆ 2</u>	(4)

- After this operation the basic variables become $(x_1, x_4 \text{ and } x_5)$
- The solution just changes to be (9,0,0,21,6,0) and the objective function increases to 27

Z	=	27	+	$\frac{x_2}{4}$	+	<u>x₃</u> 2	-	$\frac{3x_6}{4}$	(1)
<i>x</i> ₁	=	9	-	$\frac{x_2}{4}$	-	<u>x₃</u> 2	-	$\frac{x_6}{4}$	(2)
<i>x</i> ₄	=	21	-	$\frac{3x_2}{4}$	-	$\frac{5x_3}{2}$	+	$\frac{x_{6}}{4}$	(3)
<i>x</i> 5	=	6	-	$\frac{3x_2}{2}$	-	4 <i>x</i> ₃	+	<u>x₆</u> 2	(4)

- After this operation the basic variables become $(x_1, x_4 \text{ and } x_5)$
- The solution just changes to be (9,0,0,21,6,0) and the objective function increases to 27
- This too is a vertex in the convex hull

Z	=	27	+	$\frac{x_2}{4}$	+	<u>x₃</u> 2	-	$\frac{3x_6}{4}$	(1)
<i>x</i> ₁	=	9	-	<u>x₂</u> 4	-	<u>x₃</u> 2	-	$\frac{x_6}{4}$	(2)
<i>x</i> ₄	=	21	-	$\frac{3x_2}{4}$	-	<u>5x3</u> 2	+	<u>x₆</u> 4	(3)
<i>x</i> 5	=	6	-	$\frac{3x_2}{2}$	-	4 <i>x</i> ₃	+	<u>x₆</u> 2	(4)

- This operation is known as a **pivot**, which exchanges the positions of one nonbasic variable (called the **entering variable**) and one basic variable (called the **leaving variable**)
- Next we choose another entering variable (we can choose x₂ or x₃ and let's choose x₃)

Z	=	27	+	$\frac{x_2}{4}$	+	$\frac{x_3}{2}$	-	$\frac{3x_6}{4}$	(1)
<i>x</i> ₁	=	9	-	<u>x2</u> 4	-	<u>x₃</u> 2	-	$\frac{x_6}{4}$	(2)
<i>x</i> 4	=	21	-	$\frac{3x_2}{4}$	-	$\frac{5x_{3}}{2}$	+	$\frac{x_6}{4}$	(3)
									(4)

We try to increase x₃ as much as possible without increasing any non-negativity constraint

Z	=	27	+	$\frac{x_2}{4}$	+	<u>x₃</u> 2	-	$\frac{3x_{6}}{4}$	(1)
<i>x</i> ₁	=	9	-	<u>x₂</u> 4	-	<u>x₃</u> 2	-	$\frac{x_6}{4}$	(2)
<i>x</i> ₄	=	21	-	$\frac{3x_2}{4}$	-	$\frac{5x_{3}}{2}$	+	$\frac{x_6}{4}$	(3)
<i>x</i> 5	=	6	-	<u>3x2</u> 2	-	4 <i>x</i> ₃	+	<u>x₆</u> 2	(4)

- We try to increase x₃ as much as possible without increasing any non-negativity constraint
 - In (2), x₃ could be set to 18 max
 - In (3), x₃ could be set to 8.4 max
 - ▶ In (4), x₃ could be set to 1.5 max

Z	=	27	+	$\frac{x_2}{4}$	+	<u>x₃</u> 2	-	$\frac{3x_{6}}{4}$	(1)
									(2)
<i>x</i> ₄	=	21	-	$\frac{3x_2}{4}$	-	$\frac{5x_{3}}{2}$	+	$\frac{x_6}{4}$	(3)
<i>x</i> 5	=	6	-	<u>3x2</u> 2	-	4 <i>x</i> ₃	+	<u>x₆</u> 2	(4)

- Equation (4) is the tightest constraint
- We therefore switch the roles of x₃ and x₅

- Equation (4) is the tightest constraint
- We therefore switch the roles of x₃ and x₅

$$X_3 = \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8}$$

$$Z = 27 + \frac{x_2}{4} + \frac{x_3}{2} - \frac{3x_6}{4} (1)$$

$$x_1 = 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4} (2)$$

$$x_3 = \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} (3)$$

$$x_4 = 21 - \frac{3x_2}{4} - \frac{5x_3}{2} + \frac{x_6}{4} (4)$$

The current solution is (33/4, 0, 3/2, 69/4, 0, 0) with the objective value 111/4

z	=	<u>111</u> 4		<u>x₂</u> 16			-		
<i>x</i> ₁	=	$\frac{33}{4}$	-	<u>x₂</u> 16	+	<u>x</u> 5 8	-	<u>5x₆</u> 16	(2)
<i>x</i> 3	=	<u>3</u> 2	-	<u>3x2</u> 8	-	$\frac{x_5}{4}$	+	<u>x₆</u> 8	(3)
<i>x</i> ₄	=	<u>69</u> 4	+	<u>3<i>x</i>2</u> 16	+	<u>5x5</u> 8	-	<u>x₆</u> 16	(4)

- The current solution is (33/4, 0, 3/2, 69/4, 0, 0) with the objective value 111/4
- Next we increase x₂ by substituting it with x₃

z	=	<u>111</u> 4	+	<u>x₂</u> 16	-	<u>x5</u> 8	-	<u>11<i>x</i>6</u> 16	(1)
<i>x</i> ₁	=	$\frac{33}{4}$	-	<u>x2</u> 16	+	<u>x</u> 5 8	-	<u>5x₆</u> 16	(2)
<i>x</i> ₃	=	<u>3</u> 2	-	$\frac{3x_2}{8}$	-	$\frac{x_5}{4}$	+	<u>x₆ 8</u>	(3)
x ₄	=	<u>69</u> 4	+	<u>3<i>x</i>2</u> 16	+	$\frac{5x_{5}}{8}$	-	<u>x₆ 16</u>	(4)

▶ The current solution is (8,4, 0, 18, 0, 0) with the objective value 28

$$Z = 28 - \frac{x_3}{6} - \frac{x_5}{6} - \frac{2x_6}{3} (1)$$

$$x_1 = 8 + \frac{x_6}{6} + \frac{x_5}{6} - \frac{x_6}{3} (2)$$

$$x_2 = 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3} (3)$$

$$x_4 = 18 - \frac{x_3}{2} + \frac{x_6}{2} (4)$$

- ▶ The current solution is (8,4, 0, 18, 0, 0) with the objective value 28
- In the original linear program x₁ = 8, x₂ = 4 and x₃ = 0, with the objective value = 28

Ζ	=	28	-	<u>x₃</u> 6	-	<u>x₅</u> 6	-	$\frac{2x_{6}}{3}$	(1)
<i>x</i> ₁	=	8	+	<u>x₆</u> 6	+	<u>x</u> 5 6	-	<u>x₆</u> 3	(2)
<i>x</i> ₂	=	4	-	<u>8x3</u> 3	-	$\frac{2x_5}{3}$	+	<u>x₆ 3</u>	(2) (3) (4)
<i>x</i> ₄	=	18	-	<u>x₃</u> 2	+	<u>x₅</u> 2			(4)

- ▶ The current solution is (8,4, 0, 18, 0, 0) with the objective value 28
- In the original linear program x₁ = 8, x₂ = 4 and x₃ = 0, with the objective value = 28
- The slack variables measure how much slack remains within each inequality

z	=	28	-	<u>x₃</u> 6	-	<u>x₅</u> 6	-	$\frac{2x_{6}}{3}$	(1)
<i>x</i> ₁	=	8	+	<u>x₆</u> 6	+	<u>x</u> 5 6	-	<u>x₆</u> 3	(2)
<i>x</i> ₂	=	4	-	$\frac{8x_3}{3}$	-	$\frac{2x_5}{3}$	+	<u>x₆ 3</u>	(3)
x ₄									(4)

- ▶ The current solution is (8,4, 0, 18, 0, 0) with the objective value 28
- In the original linear program x₁ = 8, x₂ = 4 and x₃ = 0, with the objective value = 28
- The slack variables measure how much slack remains within each inequality
- All non-basic variables have a negative coefficient in the objective function

$$Z = 28 - \frac{x_3}{6} - \frac{x_5}{6} - \frac{2x_6}{3} (1)$$

$$x_1 = 8 + \frac{x_6}{6} + \frac{x_5}{6} - \frac{x_6}{3} (2)$$

$$x_2 = 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3} (3)$$

$$x_4 = 18 - \frac{x_3}{2} + \frac{x_6}{2} (4)$$

- ▶ The current solution is (8,4, 0, 18, 0, 0) with the objective value 28
- In the original linear program x₁ = 8, x₂ = 4 and x₃ = 0, with the objective value = 28
- The slack variables measure how much slack remains within each inequality
- All non-basic variables have a negative coefficient in the objective function
- The vertex with the maximum value is reached terminate

$$Z = 28 - \frac{x_3}{6} - \frac{x_5}{6} - \frac{2x_6}{3} (1)$$

$$x_1 = 8 + \frac{x_6}{6} + \frac{x_5}{6} - \frac{x_6}{3} (2)$$

$$x_2 = 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3} (3)$$

$$x_4 = 18 - \frac{x_3}{2} + \frac{x_5}{2} (4)$$

(N,B,A,b,c,v) = SIMPLEX (A,b,c);

 convert to slack form (N: nonbasic variable, B: basic variable)

(N,B,A,b,c,v) = SIMPLEX (A,b,c);while some index $j \in N$ has $c_j > 0$ do

- convert to slack form (N: nonbasic variable, B: basic variable)
- find a nonbasic variable that can increase the objective value

end

 $\begin{array}{l} (\mathsf{N},\mathsf{B},\mathsf{A},\mathsf{b},\mathsf{c},\mathsf{v})=\mathsf{SIMPLEX}\;(\mathsf{A},\mathsf{b},\mathsf{c});\\ \textbf{while some index}\; j\in N\; has\; c_j>0\; \textbf{do}\\ \textbf{for }each\; i\in B\; \textbf{do}\\ \Delta_i=b_i/a_{ij};\\ \textbf{end} \end{array}$

- convert to slack form (N: nonbasic variable, B: basic variable)
- find a nonbasic variable that can increase the objective value

end

 $\begin{array}{l} (\mathsf{N},\mathsf{B},\mathsf{A},\mathsf{b},\mathsf{c},\mathsf{v}) = \mathsf{SIMPLEX} \; (\mathsf{A},\mathsf{b},\mathsf{c});\\ \textbf{while some index} \; j \in \mathsf{N} \; has \; c_j > 0 \; \textbf{do} \\ \quad \textbf{for each} \; i \in B \; \textbf{do} \\ \quad \Delta_i = b_i/a_{ij};\\ \quad \textbf{end} \\ \quad \textbf{choose} \; I \in B \; \textbf{that minimises} \; \Delta_I; \end{array}$

- convert to slack form (N: nonbasic variable, B: basic variable)
- find a nonbasic variable that can increase the objective value
- find the tight basic variable

end

 $\begin{array}{l} (\mathsf{N},\mathsf{B},\mathsf{A},\mathsf{b},\mathsf{c},\mathsf{v}) = \mathsf{SIMPLEX} \ (\mathsf{A},\mathsf{b},\mathsf{c});\\ \textbf{while some index } j \in \mathsf{N} \ has \ c_j > 0 \ \textbf{do}\\ \textbf{for each } i \in B \ \textbf{do}\\ \Delta_i = b_i/a_{ij};\\ \textbf{end}\\ choose \ l \in B \ that \ minimises \ \Delta_l;\\ \textbf{if} \ \Delta_l == \inf \ \textbf{then}\\ return \ ``unbounded''\\ \textbf{else}\\ (\mathsf{N},\mathsf{B},\mathsf{A},\mathsf{b},\mathsf{c},\mathsf{v}) = \mathsf{PIVOT}(\mathsf{N},\mathsf{B},\mathsf{A},\mathsf{b},\mathsf{c},\mathsf{v},\mathsf{l},\mathsf{e})\\ \textbf{end}\\ \textbf{end}\end{array}$

- convert to slack form (N: nonbasic variable, B: basic variable)
- find a nonbasic variable that can increase the objective value
- find the tight basic variable
- replace the nonbasic with the basic variable

(N,B,A,b,c,v) = SIMPLEX (A,b,c);while some index $j \in N$ has $c_i > 0$ do for each $i \in B$ do $\Delta_i = b_i/a_{ii};$ end choose $I \in B$ that minimises Δ_I ; if $\Delta_l ==$ inf then return "unbounded" else (N,B,A,b,c,v) = PIVOT(N,B,A,b,c,v,l,e)end end for i=1..n do if $i \in B$ then $\bar{x}_i = b_i$ else $\bar{x}_i = 0$ end end return $(\bar{x_1}, \bar{x_2}, ..., \bar{x_n})$

- convert to slack form (N: nonbasic variable, B: basic variable)
- find a nonbasic variable that can increase the objective value
- find the tight basic variable
- replace the nonbasic with the basic variable
- find the values of the original variables
- return the values of original variables

Example

Solve the following linear program using the Simplex Algorithm

$$\begin{array}{ll} \text{maximise} & 18x_1 + 12.5x_2 \\ \text{subject to} & x_1 + x_2 \leq 20 \\ & x_1 \leq 12 \\ & x_2 \leq 16 \\ & x_1, x_2 \geq 0 \end{array}$$

Further Reading

Introduction to Algorithms

T.H. Cormen, C.E. Leiserson, R.L. Rivest and C. Stein. MIT Press/McGraw-Hill, ISBN: 0-262-03293-7.

- Chapter 27 Linear Programming
- Youtube Lessons Class of 2015/2016 Simplex Algorithm
 - Dylan Cope https://youtu.be/2hFdmP6fgJQ [668 views Nov 2016]
 - Oliver Crow https://youtu.be/R05477EK1XE [249 views Nov 2016]