

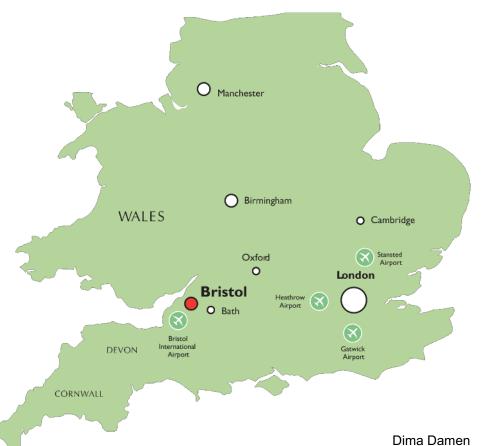
Video Understanding An Egocentric Perspective



Introduction...







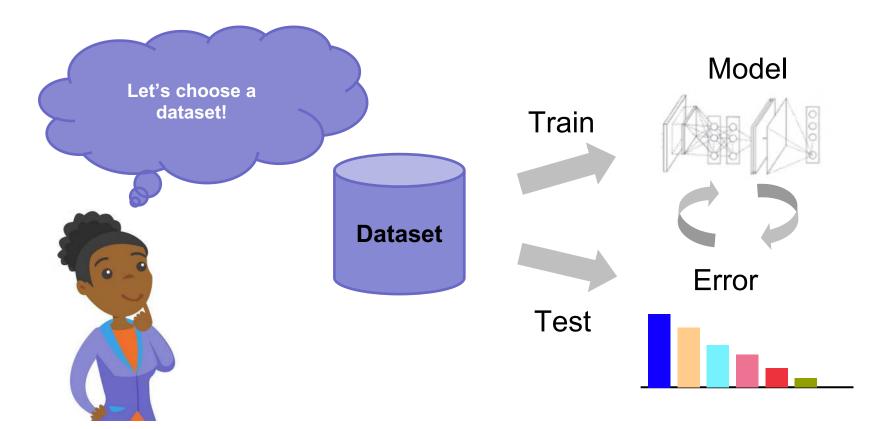


The current paradigm of Computer Vision Research



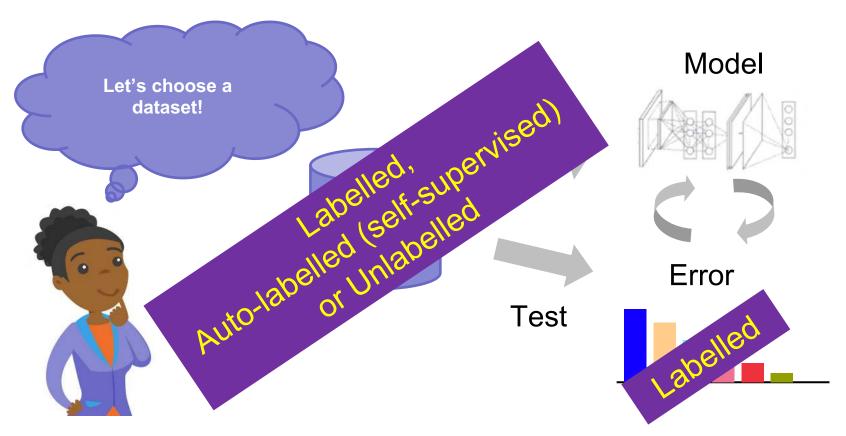


The current paradigm of Computer Vision Research



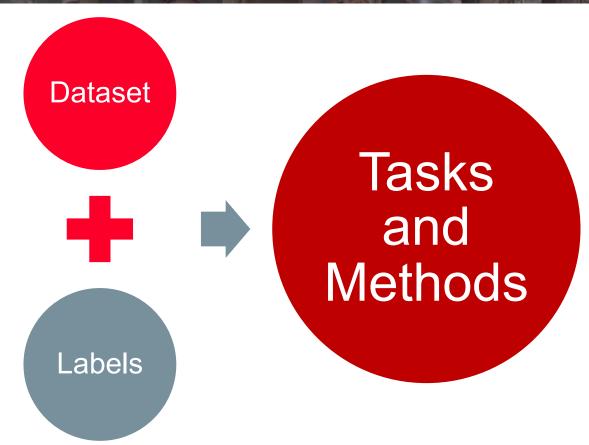


The current paradigm of Computer Vision Research

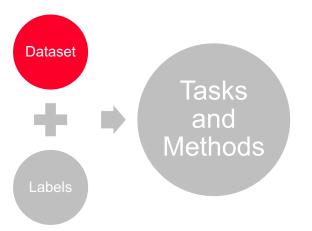




In this talk... on Video Understanding







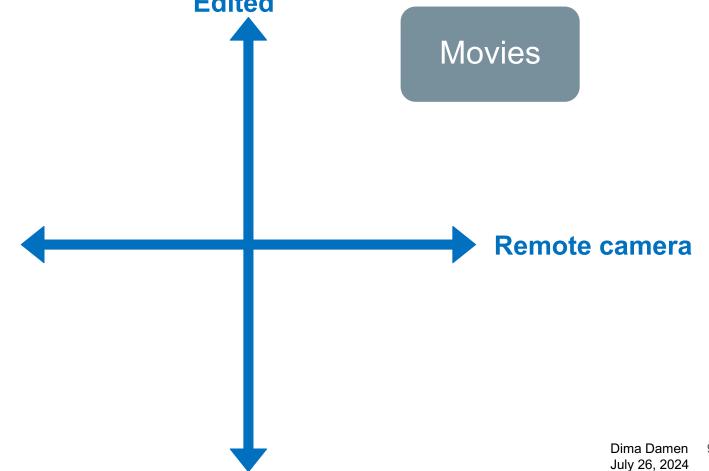
Part I: Collecting a Dataset



Our dataset is made up of... videos



The history of VIDEO understanding **Edited**



The history of VIDEO understanding



Figure 1. Examples of two action classes (drinking and smoking) from the movie "Coffee and Cigarettes". Note the high within-

Laptev and Perez (2007)



The history of VIDEO understanding







The history of VIDEO understanding **Edited** Movies Remote camera **CCTV** University of BRISTOL Dima Damen 12 July 26, 2024

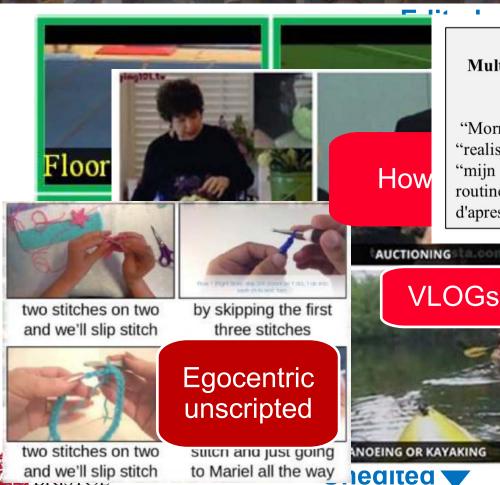
The history of VIDEO understanding







The history of video understanding



Templated, **Multilingual Domain Queries:**

"Morning routine", "realistic ditl 2015", "mijn realistische routine", "Ma routine d'apres-midi", ...

VLOGs

216K Video Candidates (2.5 Years) Low Video-level Purity



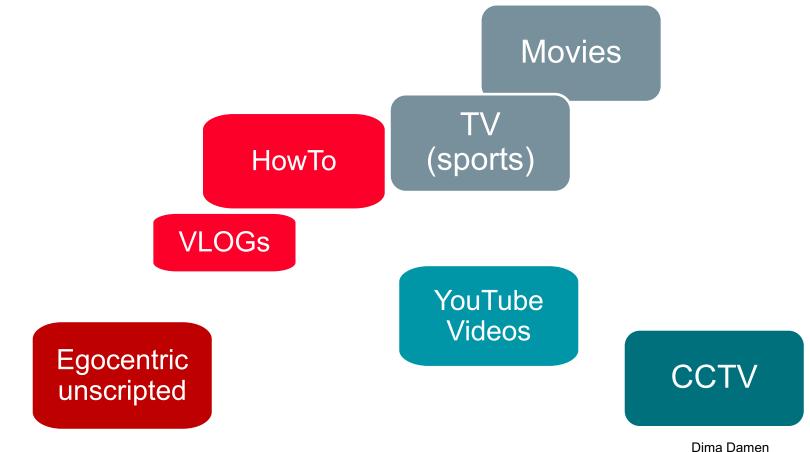
Remote camera

YouTube Videos

CCTV

Dima Damen 14 July 26, 2024

The history of Video Understanding



University of BRISTOL

July 26, 2024

Video Understanding

Speech/Plot	Movies HowTo VLOGs
Edits/Shots	Movies HowTo
Audio-Visual	Movies YouTube Egocentric
Hand-Obj	HowTo Egocentric
Guidance/ Assistance	HowTo Egocentric



The Egocentric Perspective





Egocentric Videos?





Data Collection Exercises



2017 - now

100 hours45 kitchens4 countriesLong-term recordingKitchen-based activities





2020 - now

6730 hours
923 participants
74 locations
9 countries
Short-term recording
All daily activities



Data Collection Exercises



Released Dec 2023 1422 hours 8 skilled activities 839 camera wearers Ego-Exo recordings



2024 - [coming]

[new recordings]



Ego-Exo4D

with: Kristen Grauman +102 authors

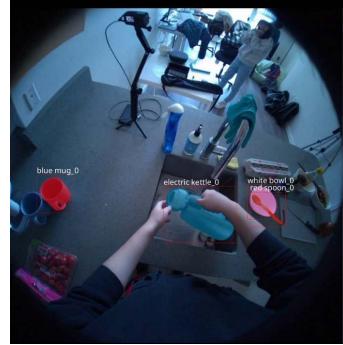




K Grauman et al (2024). Ego-Exo4D: Understanding Skilled Human Activity from First- and Third-Person Perspectives.. *CVPR*

Ego-Exo Relation

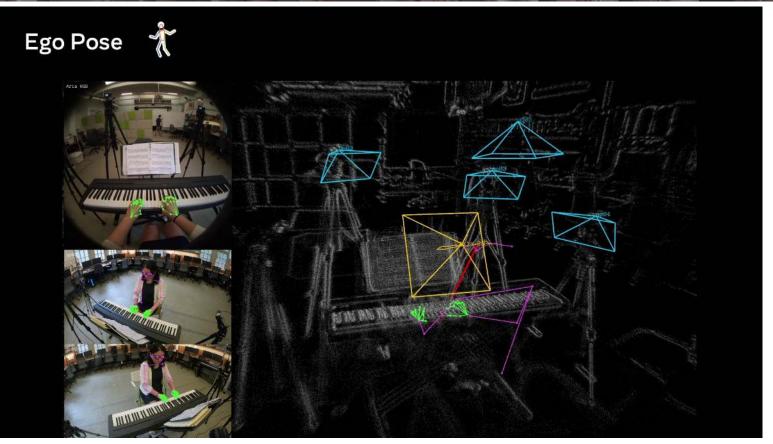




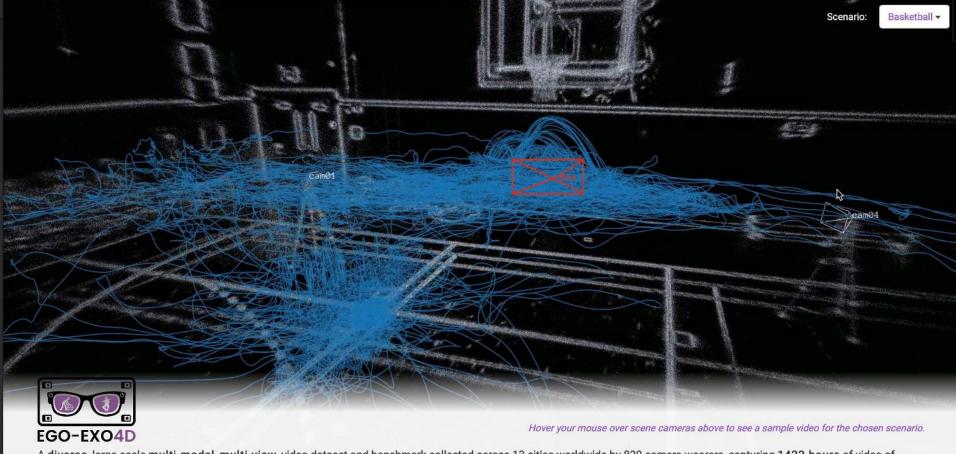




Ego-Exo4D







A diverse, large-scale multi-modal, multi-view, video dataset and benchmark collected across 13 cities worldwide by 839 camera wearers, capturing 1422 hours of video of skilled human activities.

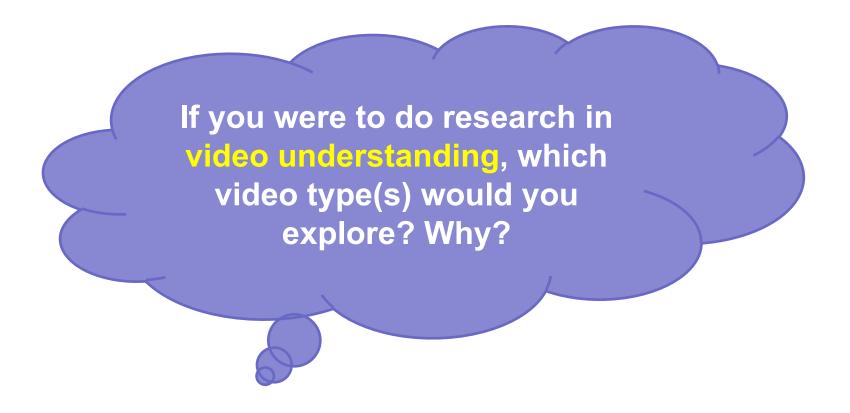
Learn More

Watch Video ↗

Start Here /

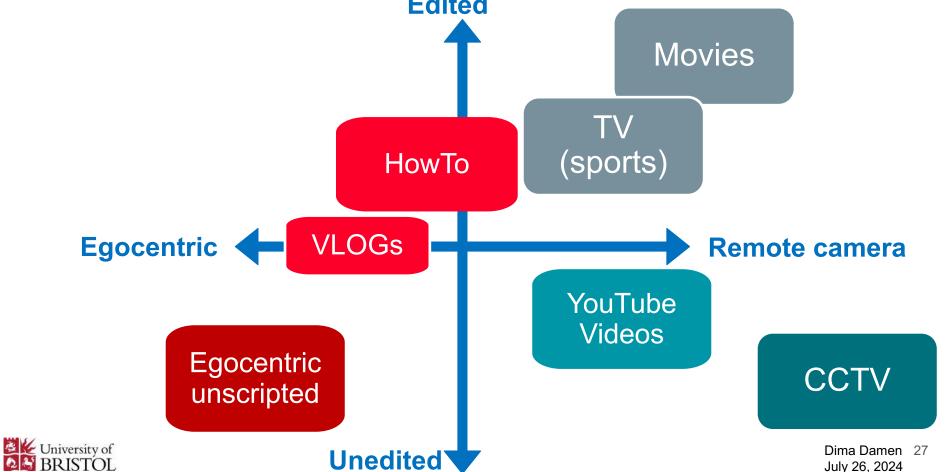








The history of VIDEO understanding Edited





sli.do

Joining as a participant?

#3639 120

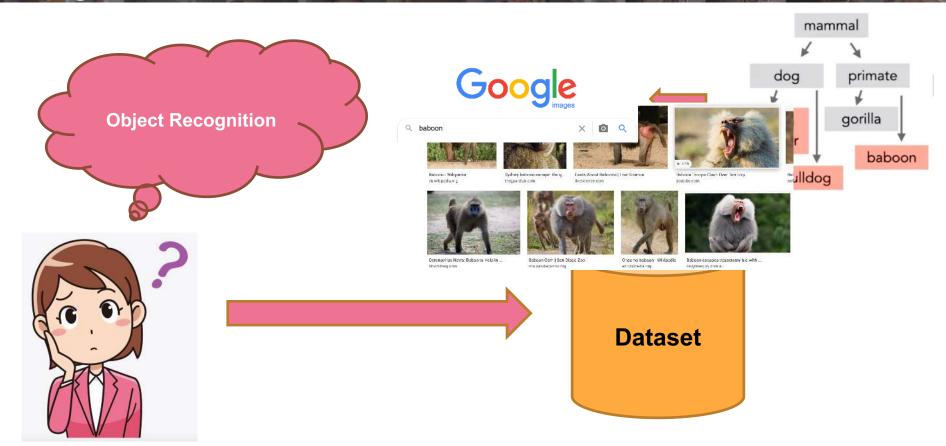








ImageNet Dataset



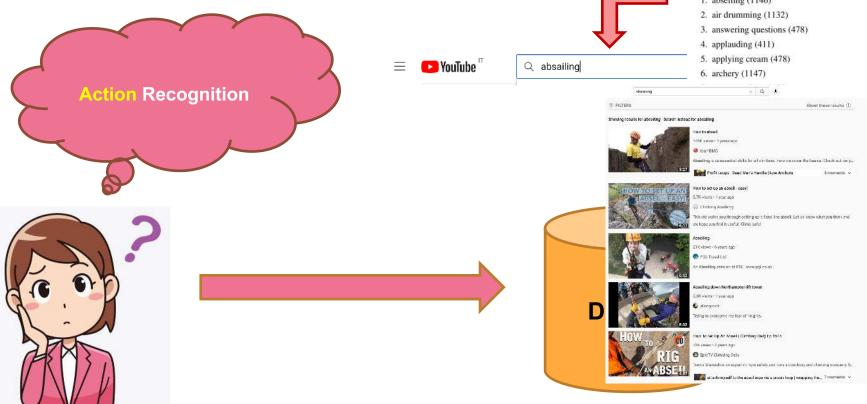


Kinetics Dataset

A. List of Kinetics Human Action Classes

This is the list of classes included in the human action video dataset. The number of clips for each action class is given by the number in brackets following each class name.

1. abseiling (1146)





Dima Damen July 26, 2024

Kinetics Dataset...

A. List of Kinetics Human Action Classes

This is the list of classes included in the human action video dataset. The number of clips for each action class is given by the number in brackets following each class name.

- 1. abseiling (1146)
- 2. air drumming (1132)
- 3. answering questions (478)
- 4. applauding (411)
- 5. applying cream (478)
- 6. archery (1147)
- 7. arm wrestling (1123)
- 8. arranging/flc as 83)
- 9. assembling mp
- 10. auctioning (478)
- 11. baby waking up (611)
- 12. baking cookies (927)
- 13. balloon blowing (826)
- 14. bandaging (569)
- 15. barbequing (1070)

Statistics: The dataset has 400 human action classes, with 400–1150 clips for each action, each from a unique video. Each clip lasts around 10s. The current version has 306,245 videos, and is divided into three splits, one for training having 250–1000 videos per class, one for validation with 50 videos per class and one for testing with 100 videos per class are given in table 2.



Machine Learning in Practice

Autonomous Driving...

Welcome to the KITTI Vision Benchmark Suite!

We take advantage of our <u>autonomous driving platform Annieway</u> to develop novel challenging real-world computer vision benchmarks. Our tasks of interest are: stereo, optical flow, visual odometry, 3D object detection and 3D tracking. For this purpose, we equipped a standard station wagon with two high-resolution color and grayscale video cameras. Accurate ground truth is provided by a Velodyne laser scanner and a GPS localization system. Our datsets are captured by driving around the mid-size city of <u>Karlsruhe</u>, in rural areas and on highways. Up to 15 cars and 30 pedestrians are visible per image. Besides providing all data in raw format, we extract benchmarks for each task. For each of our benchmarks, we also provide an evaluation metric and this evaluation website. Preliminary experiments show that methods ranking high on established benchmarks such as <u>Middlebury</u> perform below average when being moved outside the laboratory to the real world. Our goal is to reduce this bias and complement existing benchmarks by providing real-world benchmarks with novel difficulties to the community.





BRISTOL

To get started, grab a cup of your favorite beverage and watch our video trailer (5 minutes):

Machine Learning in Practice



Let's collect Data!













Scaling and Rescaling Egocentric Vision: The EPIC-KITCHENS Dataset



























EPIC-KITCHENS





Scaling and Rescaling Egocentric Vision

- Head-Mounted Go-Pro, adjustable mounting
- Recording starts immediately before entering the kitchen
- Only stopped before leaving the kitchen



EPIC-KITCHENS



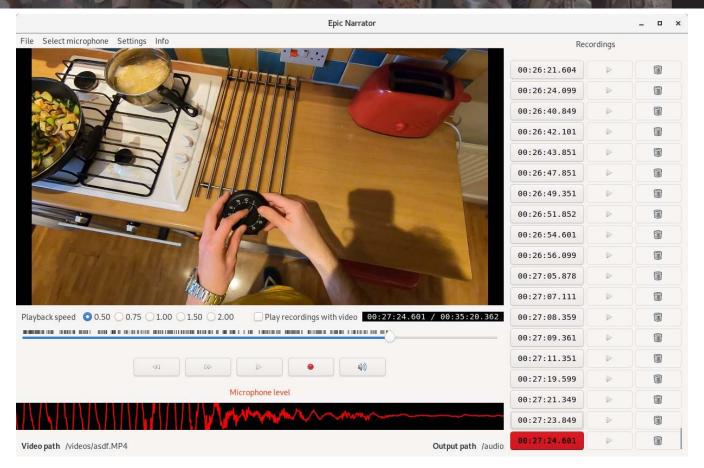


Dima Damen July 26, 2024



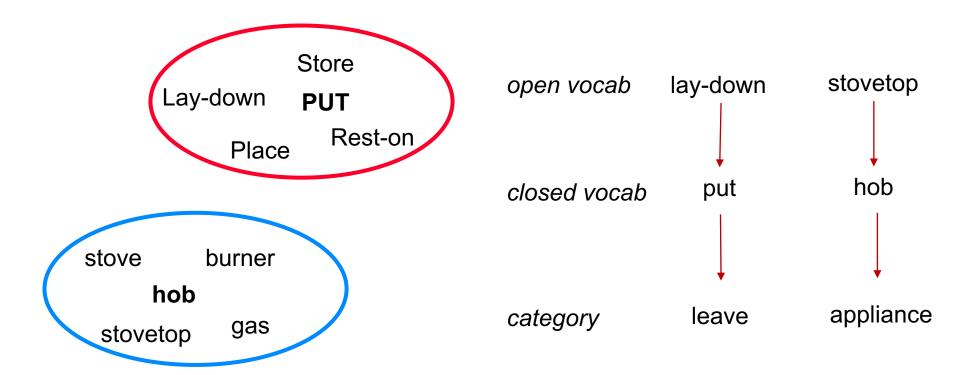


EPIC-KITCHENS



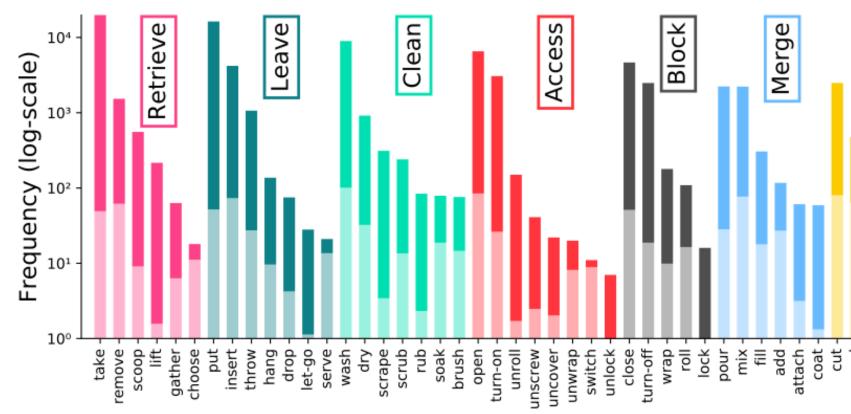


EPIC-KITCHENS and Ego4D





EPIC-KITCHENS-100 Statistics





Dima Damen July 26, 2024

Ego4D

Narration

C: camera wearer

#C C scraps off wood filler from one putty knife with the other putty knife #C C picks up another putty knife from the white board

13.2 sentences/min3.8 M sentences

1,772 verbs



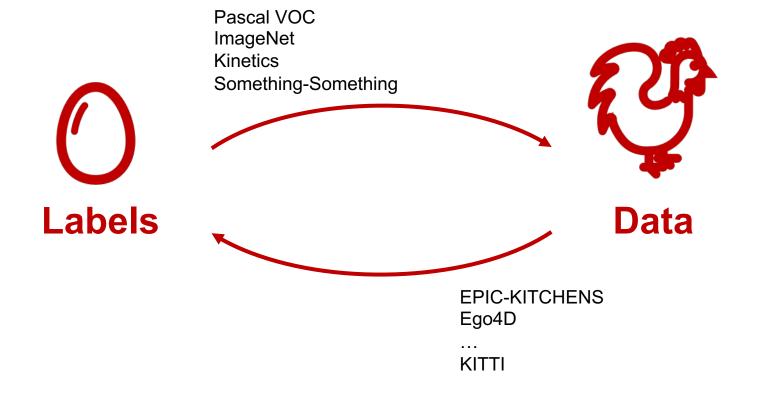
4,336 nouns







Data Collection Exercise





The chicken or the egg...







Naturally unbalanced

Harder to label (exposes ambiguity)

Closer to application

Multiple tasks

Unnaturally balanced (or nearly)

Easier to label (hides ambiguity)

Can be expanded

Single task

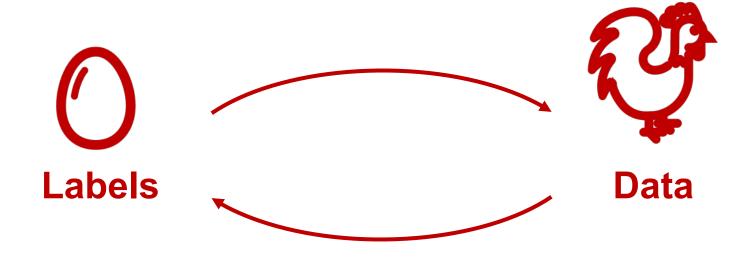






Data Collection Exercise

What should come first? Labels or Data







sli.do

Joining as a participant?

#3639 120

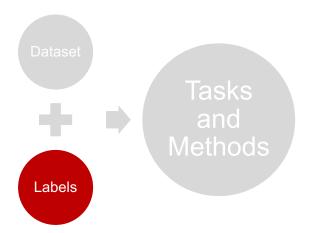






Video source and data collection approach heavily infl_{uences} video understanding tasks





Part II: Labelling a Dataset



What type of labels can we provide?

- Temporal labels Strong vs. Weak labels
- Semantic labels Open-vocab. vs Closed-vocabulary
- Ranking labels video-to-video comparisons
- Pixel-level labels segmentation labels



What type of labels can we provide?

- Temporal labels Strong vs. Weak labels
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- Ranking labels video-to-video comparisons
- Pixel-level labels segmentation labels



Action Recognition Challenge



Given a trimmed action segment: $(t_{
m start}, t_{
m stop})$

classify the action within.

$$\hat{y}_{\mathrm{verb}} = \mathsf{open}$$

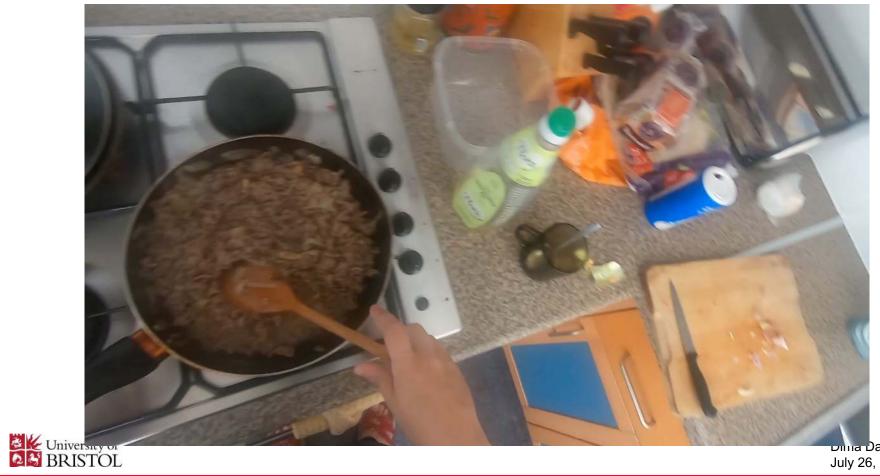
$$\hat{y}_{ ext{noun}} = \mathsf{oven}$$

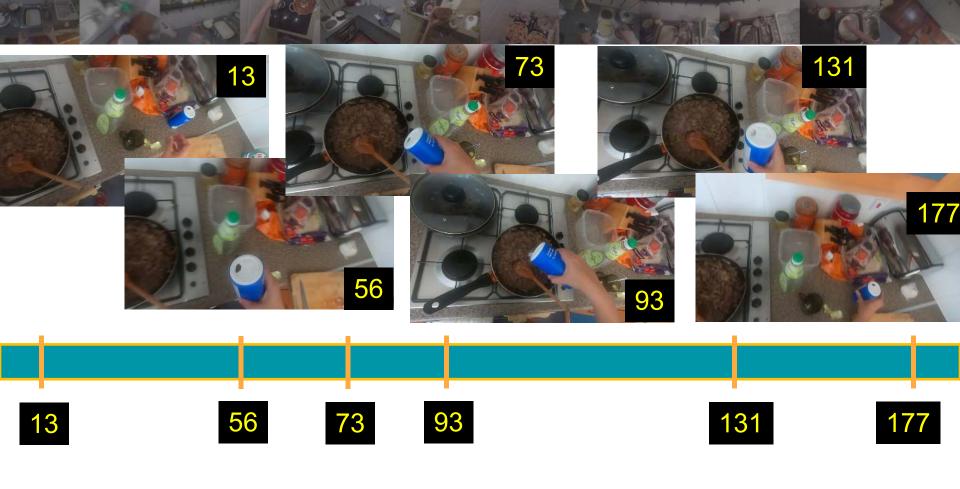
$$\hat{y}_{
m action} = ext{(open, oven)}$$



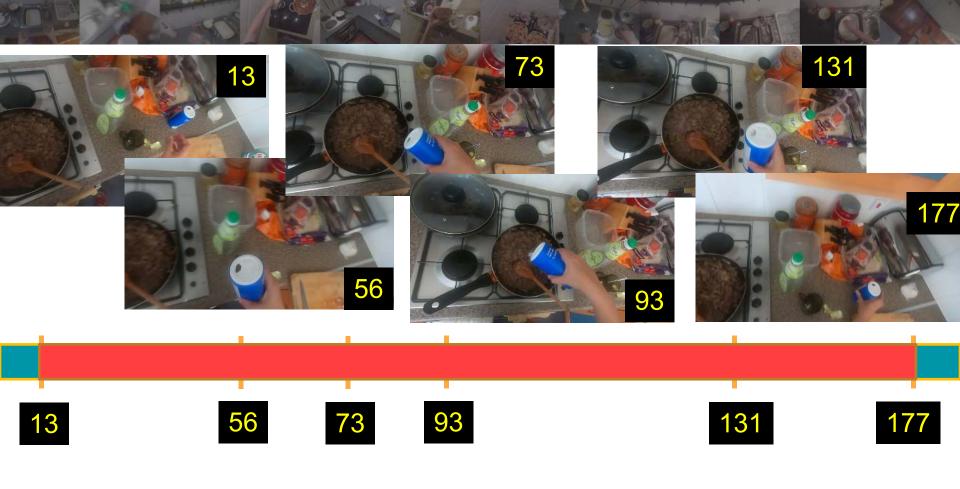




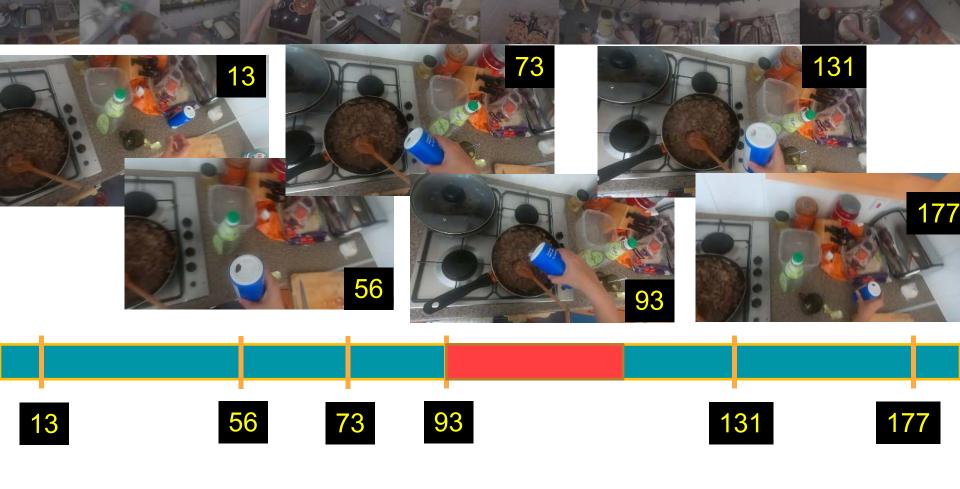




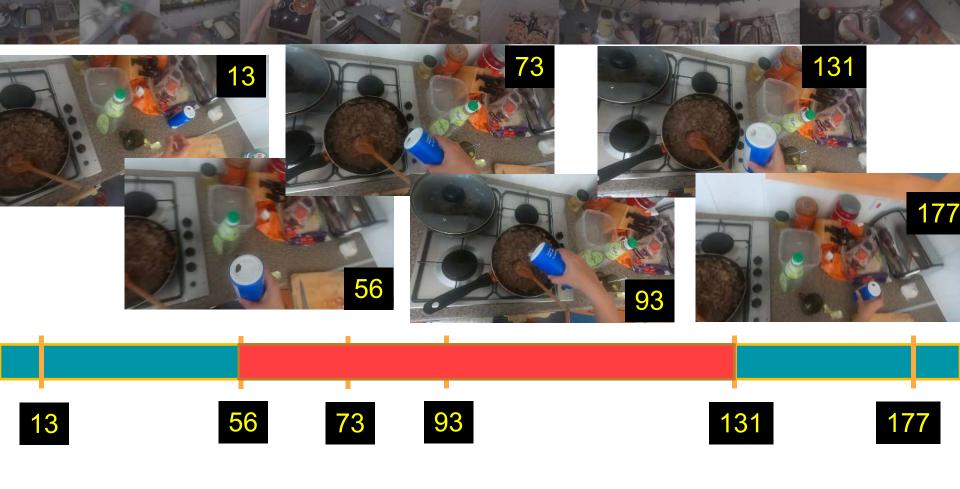




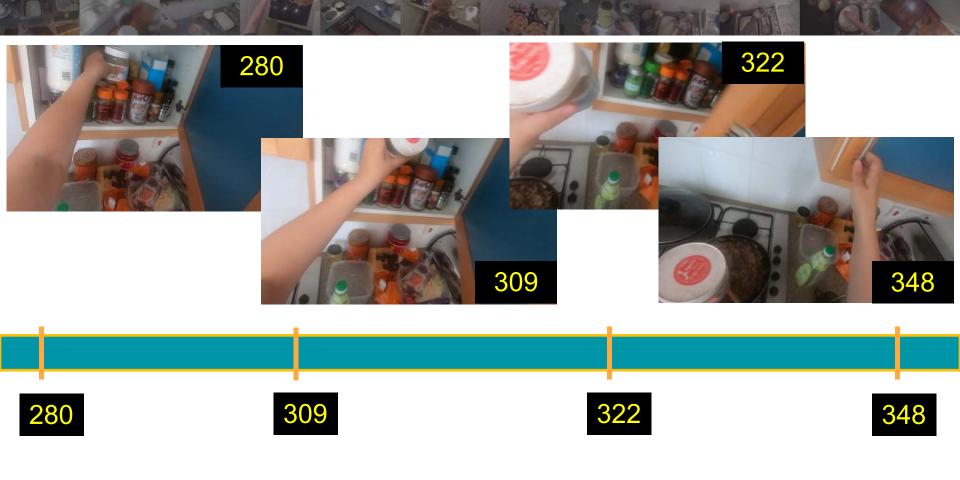




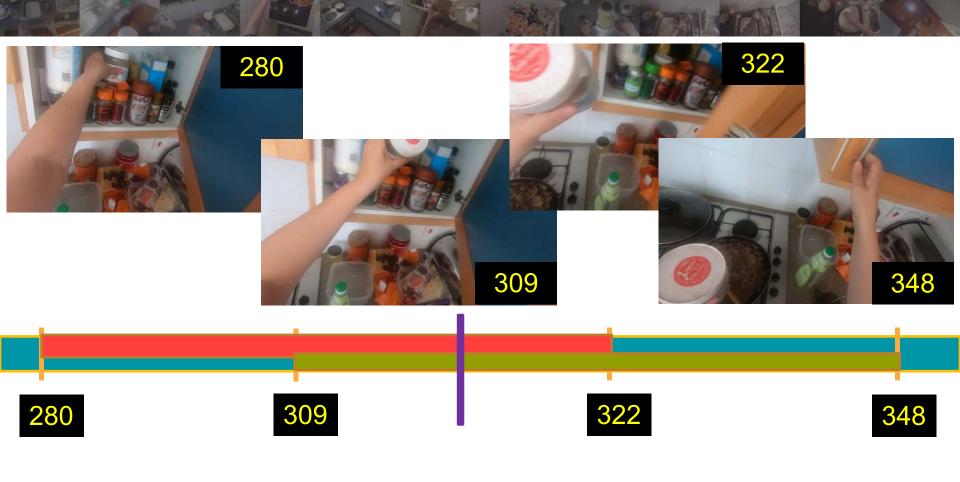














Inconsistencies of temporal bounds across datasets for the same action

BEOID: take cup





GTEA Gaze+

ground truth



predicted class: take knife

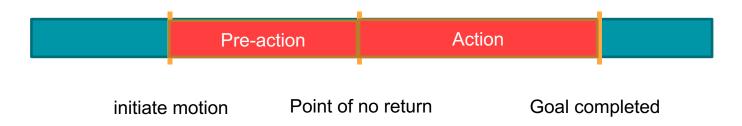






- [A] There are two stages of an action, separated by three boundary points
 - Pre-action stage:
 - Action stage:





[A] P. M. Gollwitzer (1990). Action phases and mind-sets. Handbook of motivation and cognition.



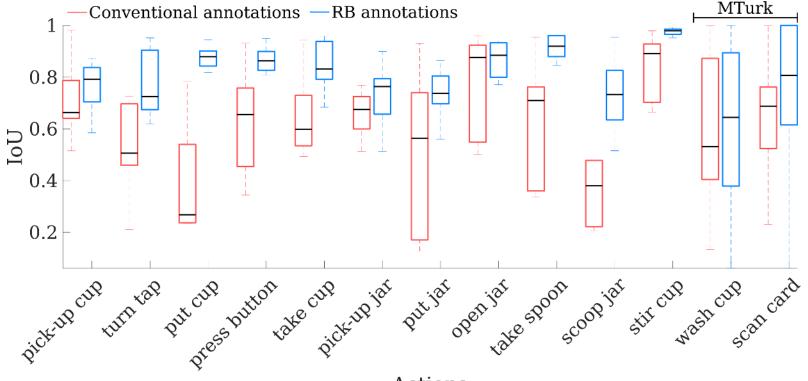




Rubicon Boundaries

Now we show some object interactions segmented by multiple annotators using conventional labeling, along with the same actions labeled by different annotators following the Rubicon Boundaries (ref. Figure 3).





Actions



The power of temporal labels



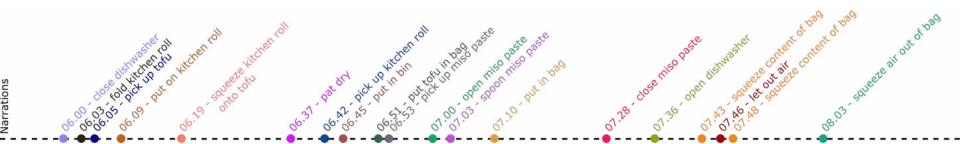


Other approaches to temporal boundaries

- Start-and-end times
 - Inconsistent
 - Consistent
- Fixed segment lengths
 - Kinetics Dataset -- 10 seconds videos
 - Moments in Time Dataset 3 seconds videos
- No temporal annotations
 - Charades Dataset Video-Level supervision (3-4 actions per video)
- Single-timestamp supervision

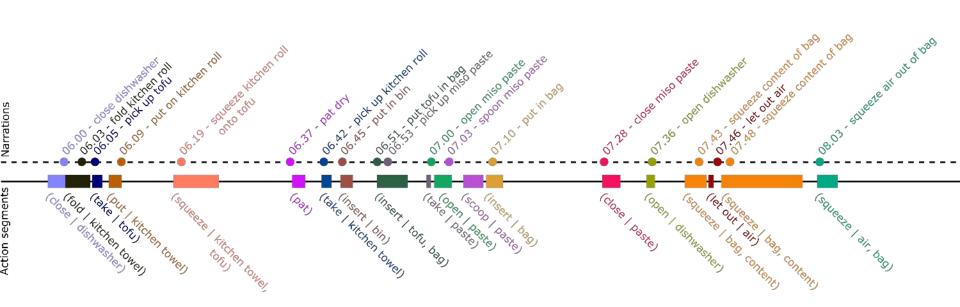


Scaling and Rescaling Egocentric Vision

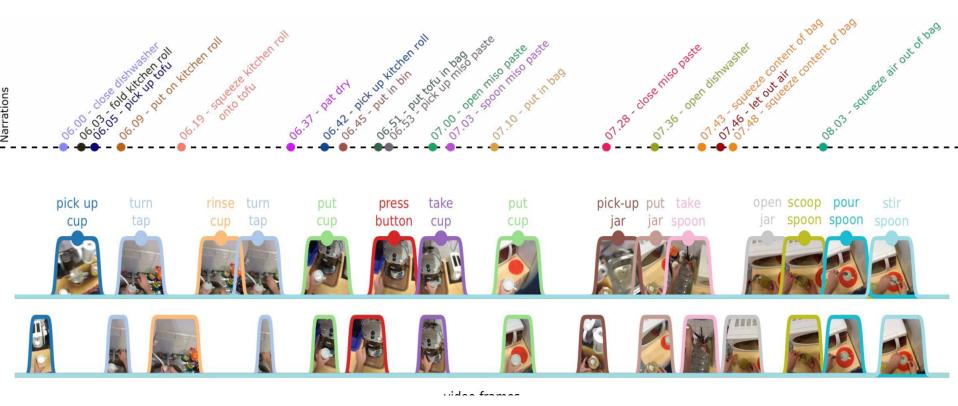




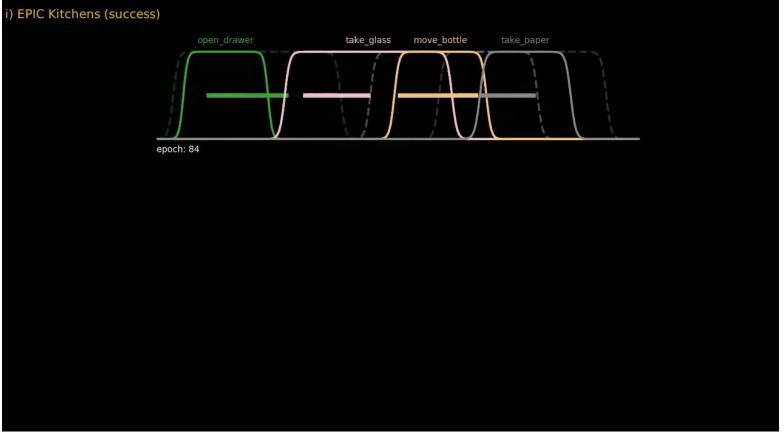
Scaling and Rescaling Egocentric Vision



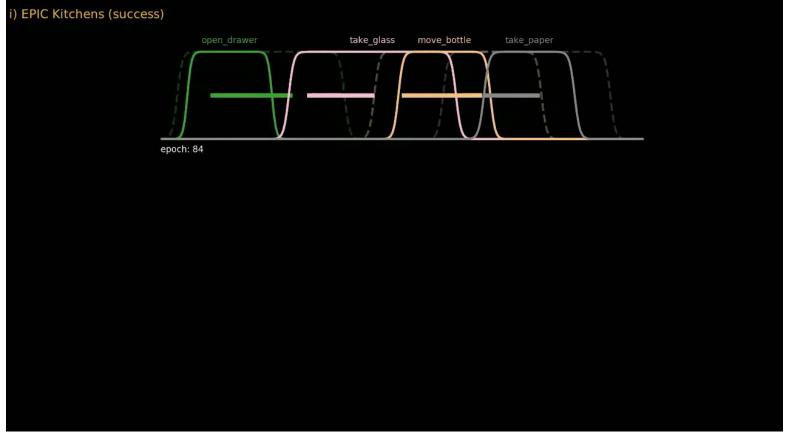




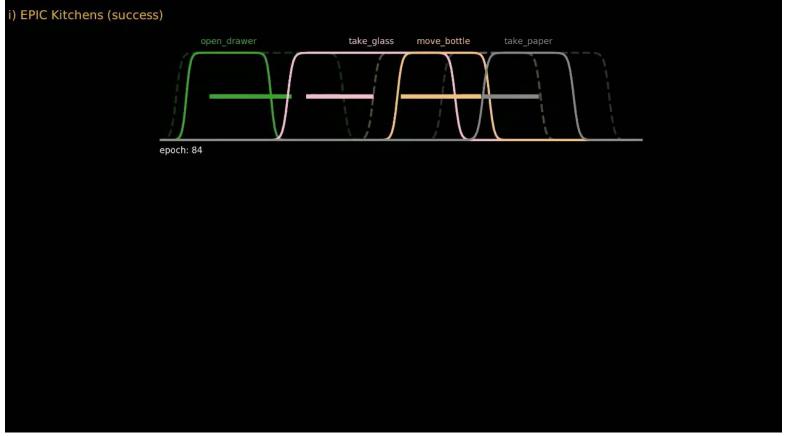




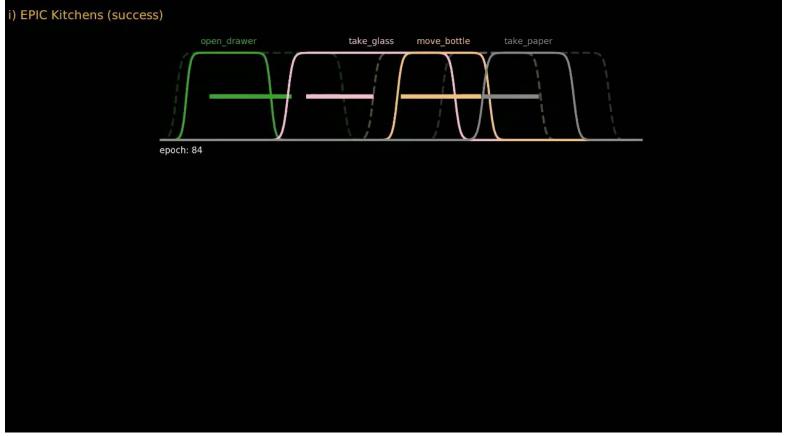








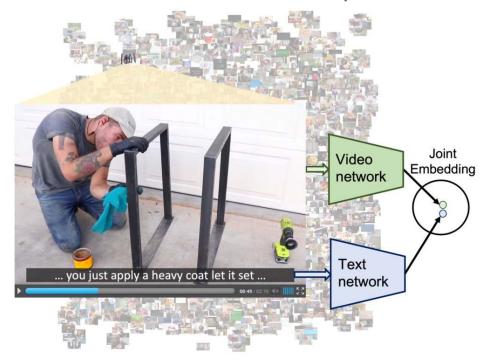






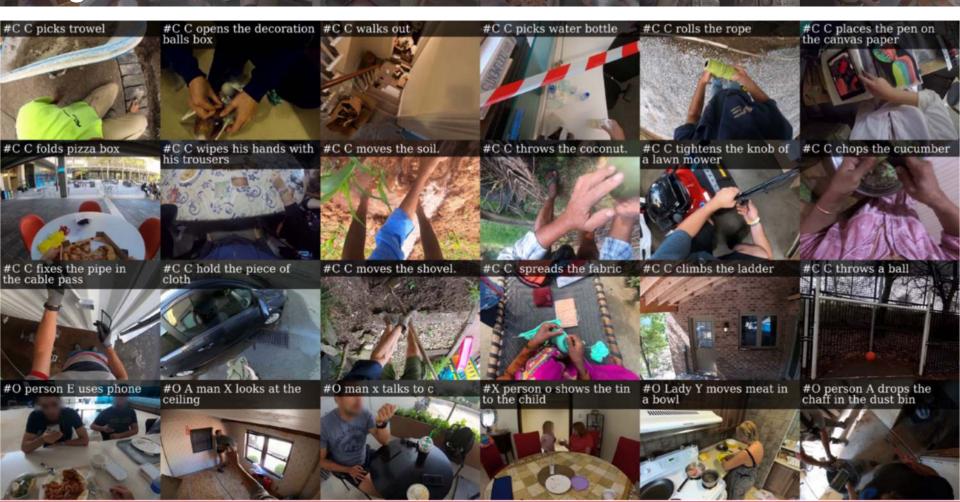
Learning from a Narration Timestamps

Miech et al (2019). HowTo100M: Learning a Text-Video Embedding by Watching Hundred Million Narrated Video Clips





Ego4D



with: Kristen Grauman +83 authors



Temporal labels vary across consistent











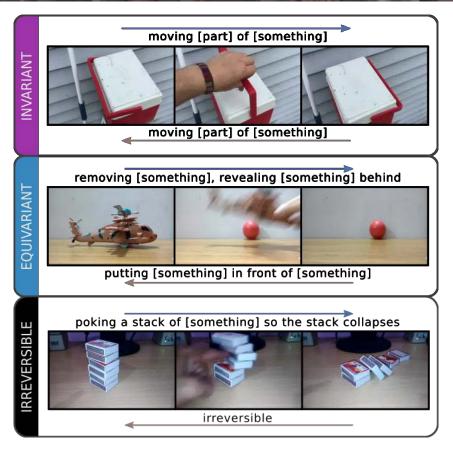


This CVPR2014 paper is the Open Access version, provided by the Computer Vision Foundation. The authoritative version of this paper is available in IEEE Xplore.

Seeing the Arrow of Time

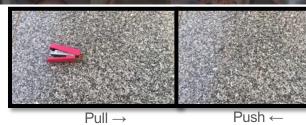
Zheng Pan² Donglai Wei³ YiChang Shih³ Lyndsey C. Pickup¹ Changshui Zhang² Andrew Zisserman¹ Bernhard Schölkopf⁴ William T. Freeman³



















Removing _

revealing _

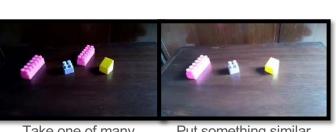
behind

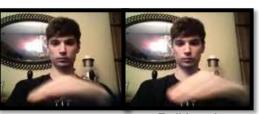
Moving and so they pass each other

Trying to bend _ unbendable

Putting _ in front of _







Swipe
University of BRISTOL

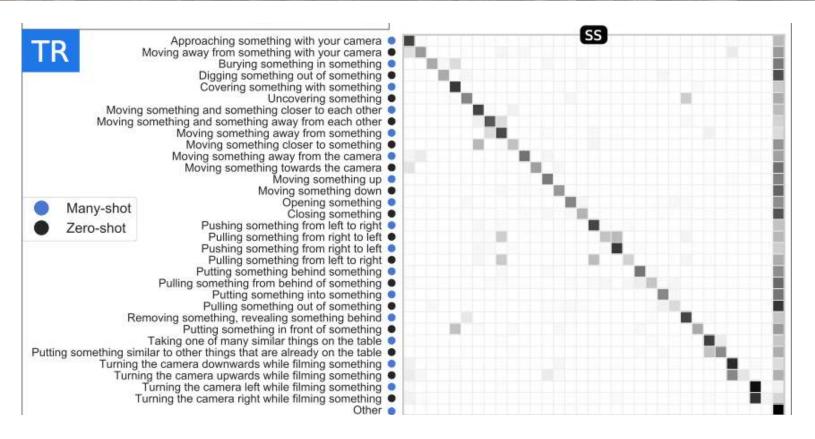
Swipe Take one of many similar things on the table

Put something similar to other things already on the table

Roll hand Roll hand forward Dil band July 26, 2024



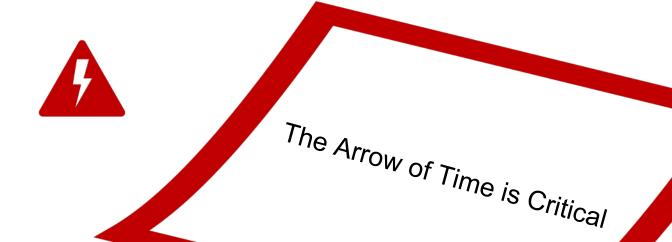






Now, results from a model supervised by time-reversal example synthesis











The magic of audio-visual understanding...

 Object-Object interactions





Multi-modal learning...

 The magic of audio-visual understanding...

- Object-Object interactions
- Material sounds

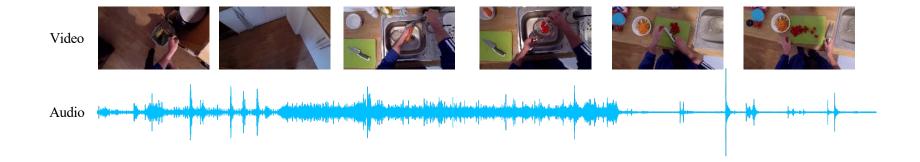


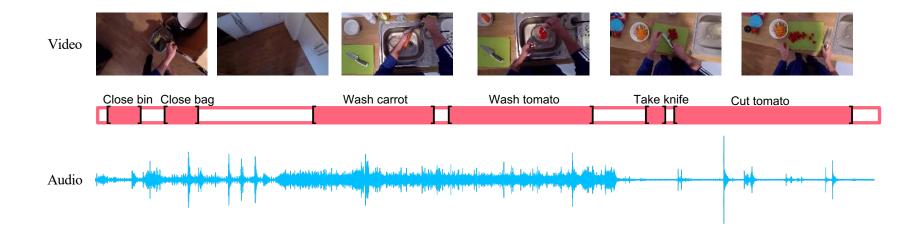


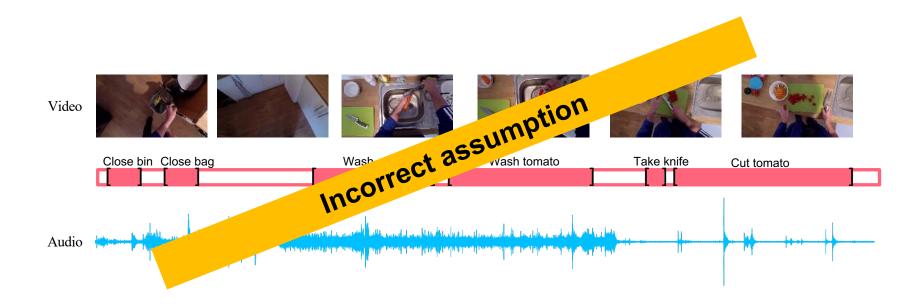
- The magic of audio-visual understanding...
- Object-Object interactions
- Material sounds
- Sound-emitting objects

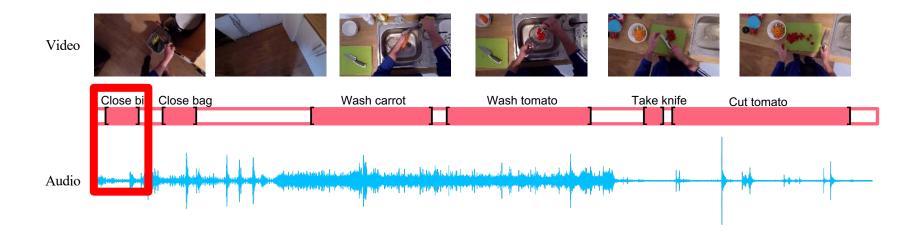


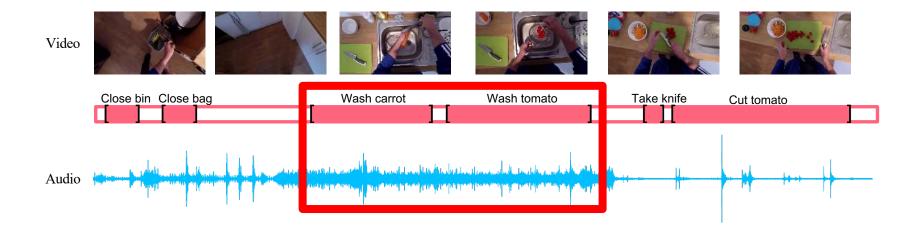


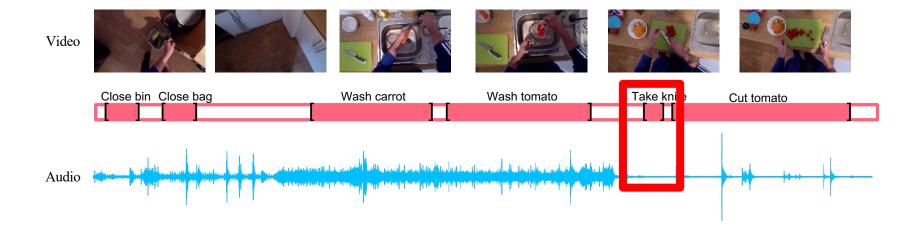


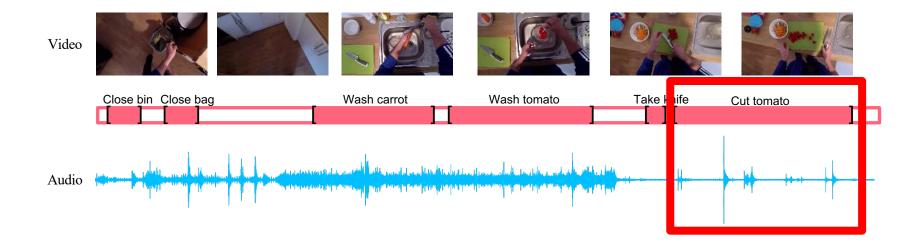


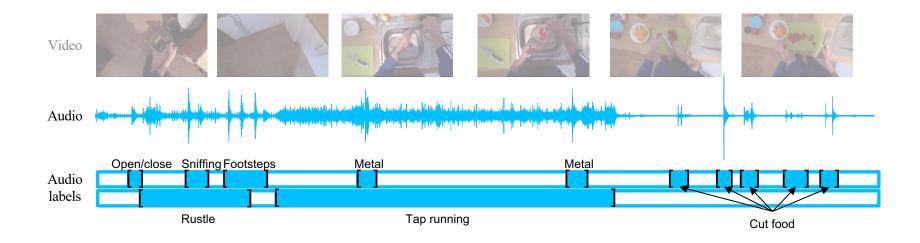


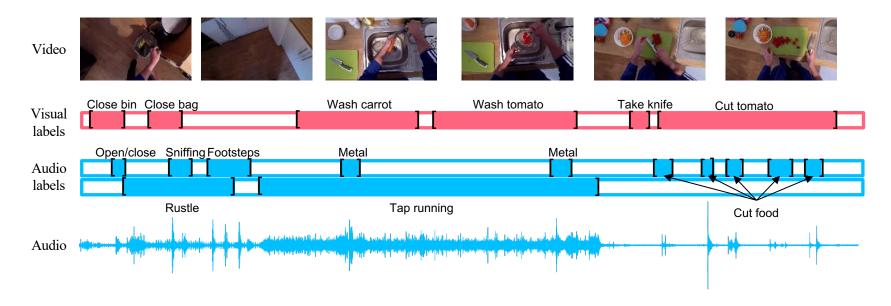














EPIC-KITCHENS VIDEOS 100 hours 45 kitchens

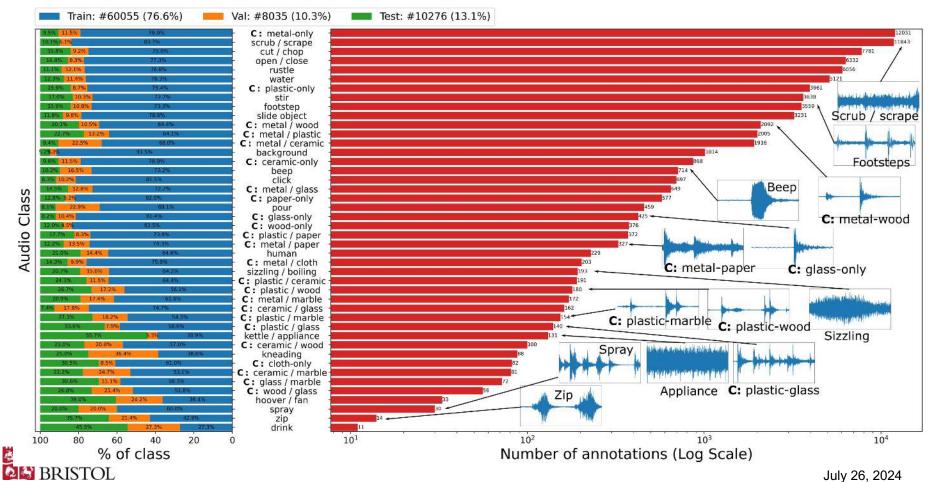
Visual Action Annotations
90K visual actions
97 verb classes
300 noun classes

EPIC-Sounds
Audio-Based Annotations
79K categorised audio events
44 sound categories
39K uncategorised events

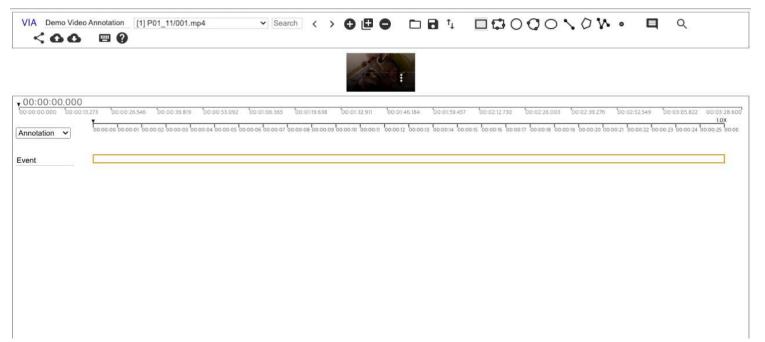


EPIC-SOUNDS

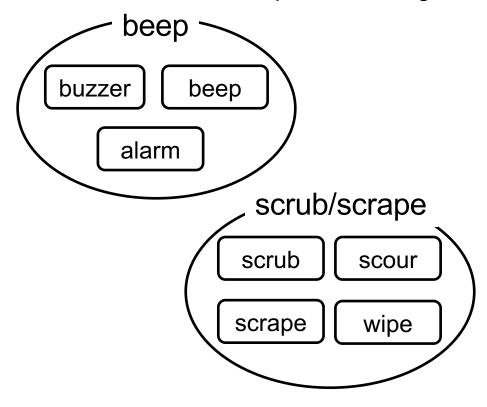
with: Jaesung Huh* & Jacob Chalk* Vangelis Kazakos Andrew Zisserman



- We annotate all the distinctive sound events which consist of temporal intervals using free-form sound descriptions.
- Using VGG Image annotator tool



From free-form descriptions to categories

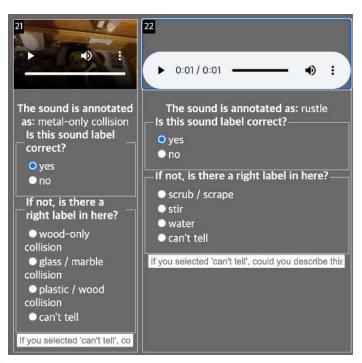




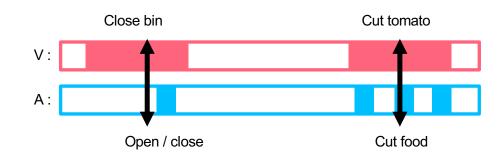
- For collision sounds, we annotate the <u>materials</u> of the objects that colliding.
- Materials example



Manual check on validation / test set



• We use the overlaps between audio and visual segments for reviewing train set.





Temporal labels are modality-specific!



What type of labels can we provide?

- Temporal labels Strong vs. Weak labels
- Semantic labels Open-vocab. vs Closed-vocabulary
- Ranking labels video-to-video comparisons
- Pixel-level labels segmentation labels









Verb?

Noun?





sli.do

Joining as a participant?

#3639 120







Verbs:

add pour sprinkle salt season





Nouns: salt

sea salt seasoning salt granules

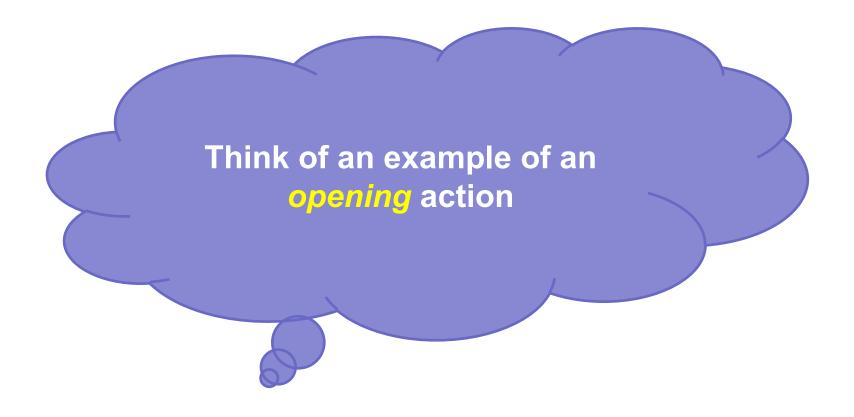






sprinkle salt season meat

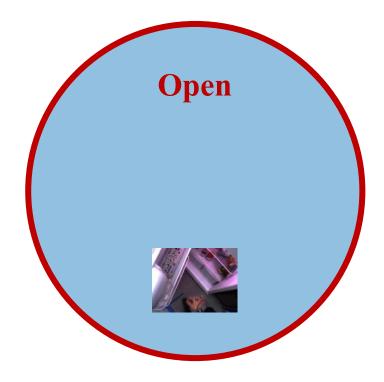








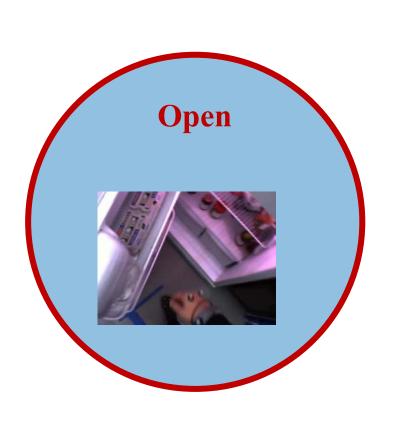


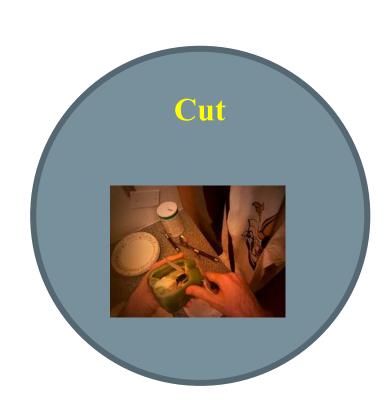








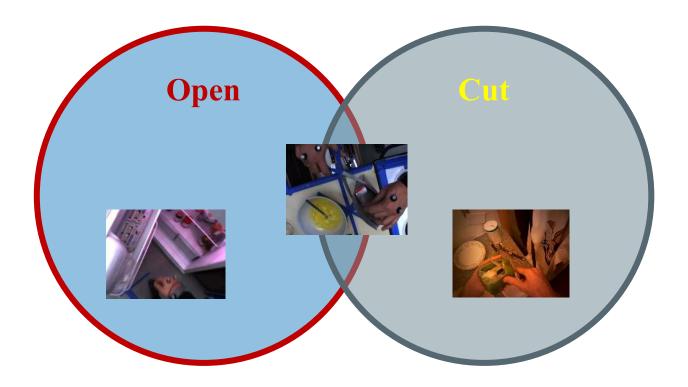














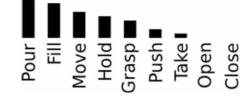
Towards an unequivocal rep. of actions

- Action representations using a single verb is highly-ambiguous
 - Solution1: pre-selected non-overlapping verbs (SL)
 - run, walk, open, close
 - Solution2: Using nouns to disambiguate actions (V-N)
 - open-drawer, open-bottle, open-fridge
 - actions constrained to known nouns
 - Solution3: Multi-verb labels (ML, SAML)
 - open, hold, pull



Towards an unequivocal rep. of actions

Collected from AMT



SL

- Majority Vote.
- One-hot vector.

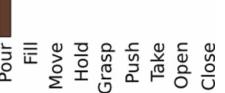
Pour Fill Move Hold Grasp Push Take Open

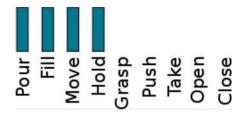
ML

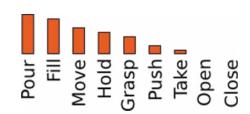
- Threshold of 0.5.
- **Binary Vector**

SAML

- Full Annotation.
- Continuous Vector.









Towards an unequivocal rep. of actions

Top 3 retrieved classes across all datasets.



Labelling Method can differentiate turn On/Off tap by pressing and by rotating.





Semantics are harder than You think...
There are significant



What type of labels can we provide?

- Temporal labels Strong vs. Weak labels
- Semantic labels Open-vocab. vs Closed-vocabulary
- Ranking labels video-to-video comparisons
- Pixel-level labels segmentation labels



Quality of Actions...



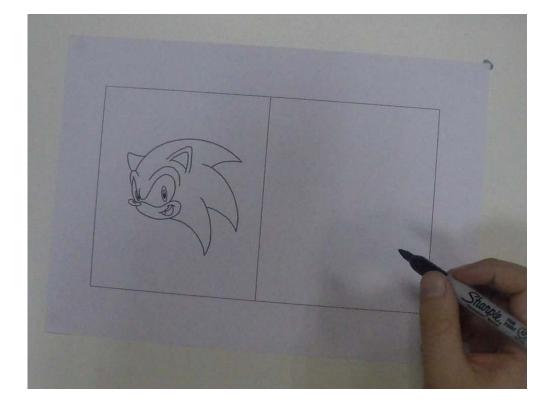
Pirsiavash et al, ECCV 2014



Shao et al, CVPR 2020



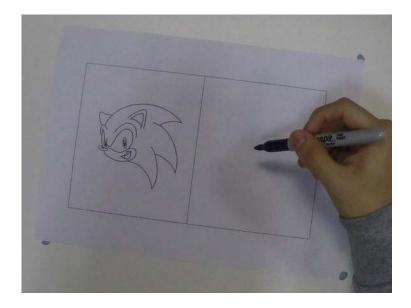
Quality of Actions...

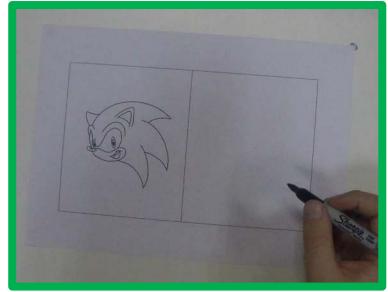




Skill determination in video

Pairwise annotations of videos, indicating higher skill or no skill preference





What type of labels can we provide?

- Temporal labels Strong vs. Weak labels
- Semantic labels Open-vocab. vs Closed-vocabulary
- Ranking labels video-to-video comparisons
- Pixel-level labels segmentation labels

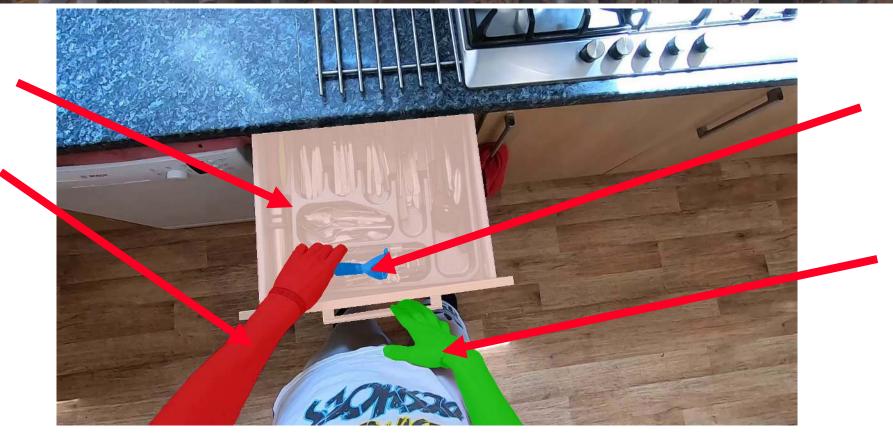


with: Ahmad Darkhalil, Dandan Shan, Bin Zhu, Jian Ma, Amlan Kar, Richard Higgins, David Fouhey, Sanja Fidler





with: Ahmad Darkhalil, Dandan Shan, Bin Zhu, Jian Ma, Amlan Kar, Richard Higgins, David Fouhey, Sanja Fidler



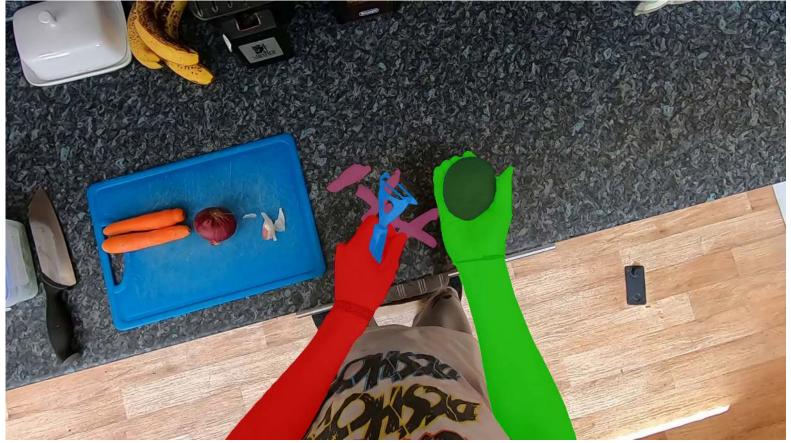








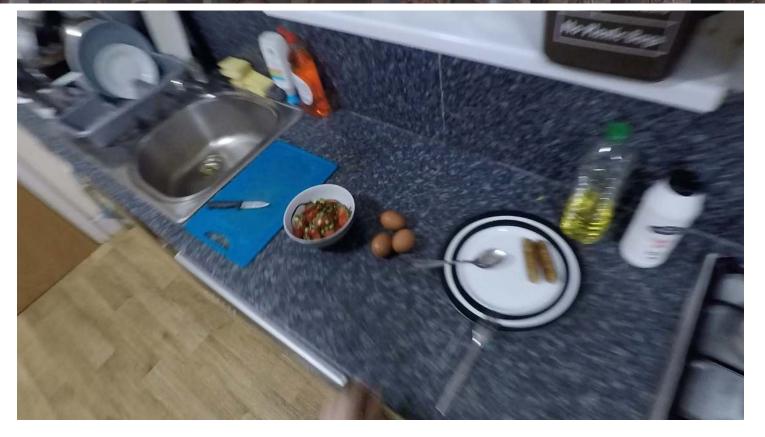
with: Ahmad Darkhalil, Dandan Shan, Bin Zhu, Jian Ma, Amlan Kar, Richard Higgins, David Fouhey, Sanja Fidler





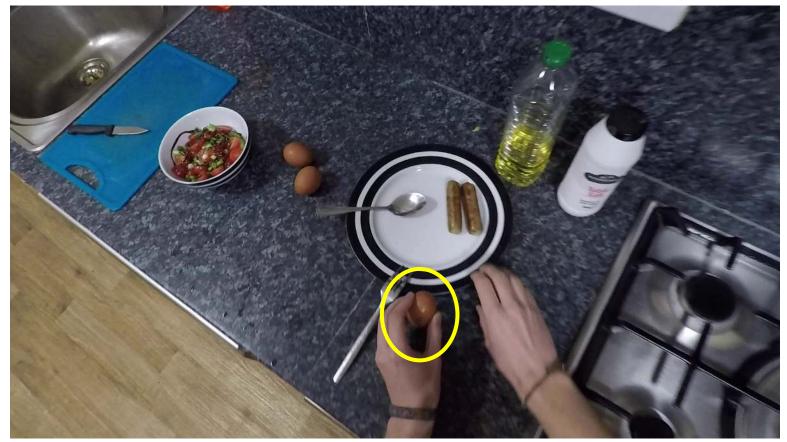


with: Ahmad Darkhalil, Dandan Shan, Bin Zhu, Jian Ma,
Amlan Kar, Richard Higgins, David Fouhey, Sanja Fidler





with: Ahmad Darkhalil, Dandan Shan, Bin Zhu, Jian Ma,
Amlan Kar, Richard Higgins, David Fouhey, Sanja Fidler





with: Ahmad Darkhalil, Dandan Shan, Bin Zhu, Jian Ma,
Amlan Kar, Richard Higgins, David Fouhey, Sanja Fidler





EPIC-KITCHENS VISOR

with: Ahmad Darkhalil, Dandan Shan, Bin Zhu, Jian Ma,
Amlan Kar, Richard Higgins, David Fouhey, Sanja Fidler

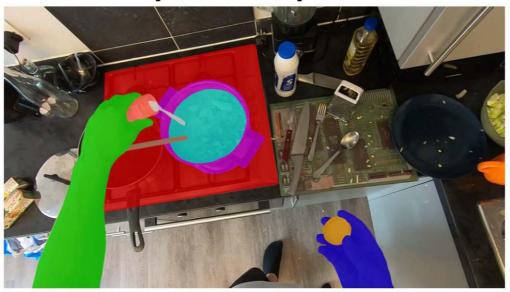




EPIC-KITCHENS VISOR with: Ahmad Darkhalil, Dandan Shan, Bin Zhu, Jian Ma, Amlan Kar, Richard Higgins, David Fouhey, Sanja Fidler No Plas.



pour spice



left hand right hand

hob saucepan

spice spice container

spoon soup

pepper container lid



VISOR is....

pour spice





VISOR is....

pour spice



left hand right hand

hob saucepan

spice spice container

spoon soup

pepper container lid







- lleft hand **m**right hand
- lhob Isaucepan
- spice [spice container
- spoon soup
- pepper container lid

in-contact (spige-eentainer lid)



VISOR is....

pour spice



spoon (non-exhaustive)



EPIC-KITCHENS VISOR

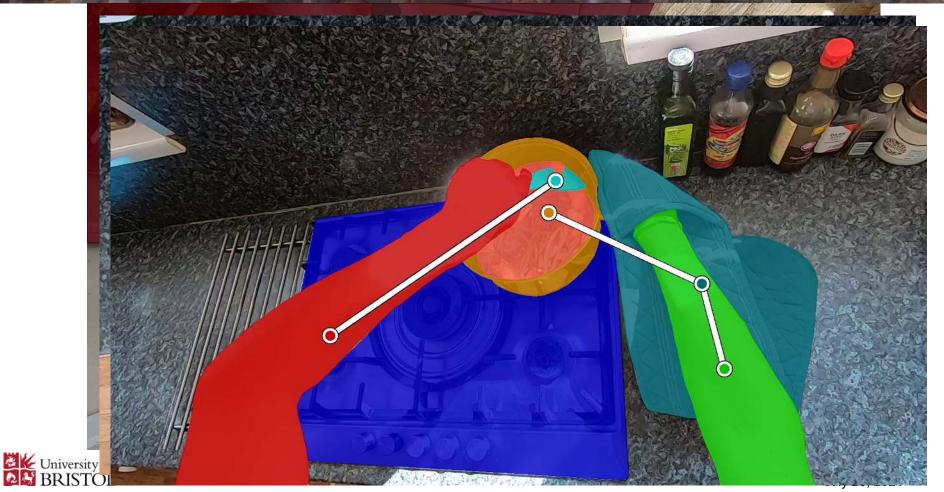
with: Ahmad Darkhalil, Dandan Shan, Bin Zhu, Jian Ma, Amlan Kar, Richard Higgins, David Fouhey, Sanja Fidler





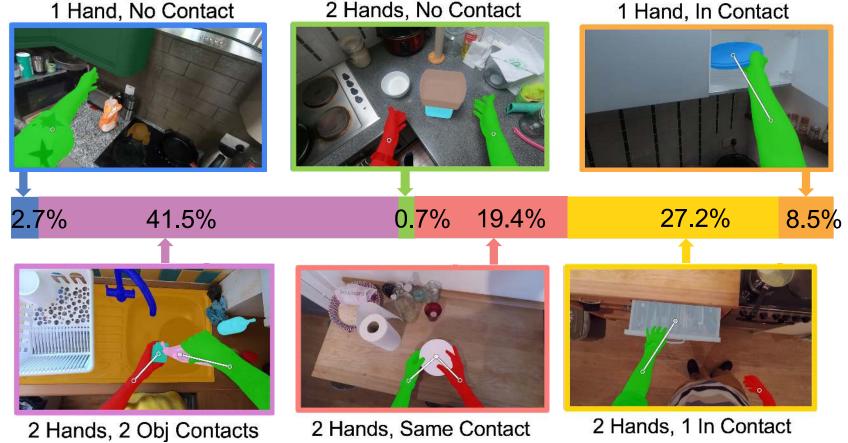
VISOR Relations

with: Ahmad Darkhalil, Dandan Shan, Bin Zhu, Jian Ma, Amlan Kar, Richard Higgins, David Fouhey, Sanja Fidler, Dima Damen



Object relation stats

with: Ahmad Darkhalil, Dandan Shan, Bin Zhu, Jian Ma, Amlan Kar, Richard Higgins, David Fouhey, Sanja Fidler, Dima Damen





EPIC-KITCHENS VISOR

with: Ahmad Darkhalil, Dandan Shan, Bin Zhu, Jian Ma,
Amlan Kar, Richard Higgins, David Fouhey, Sanja Fidler

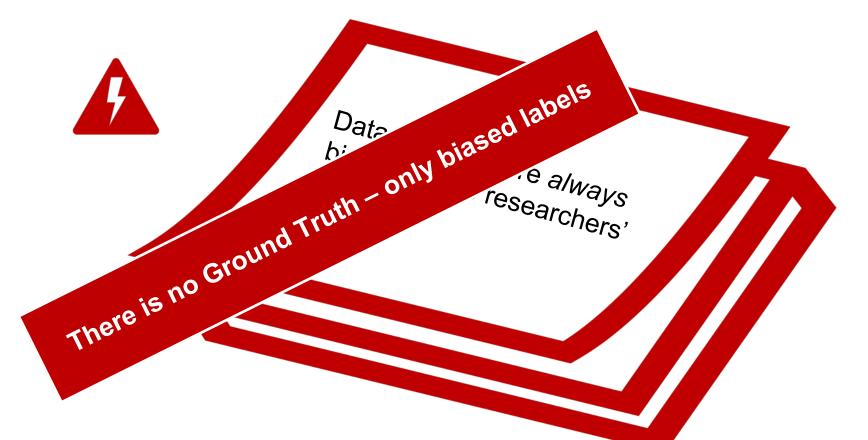




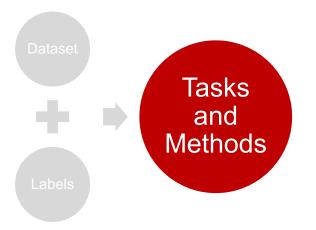


Semantic segmentations during transformations is...









Part III: Tasks and Methods

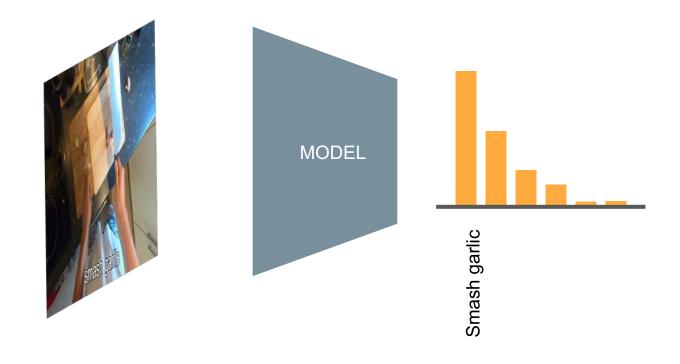




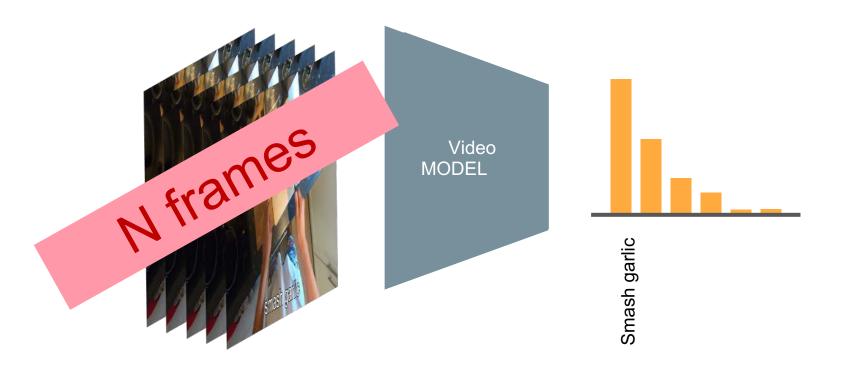














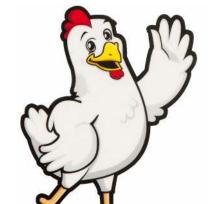




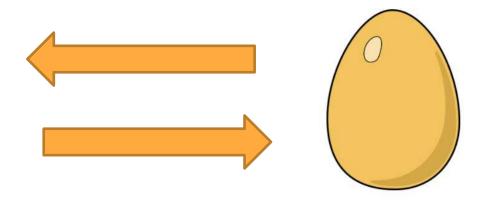




Frames to select



Action to recognise



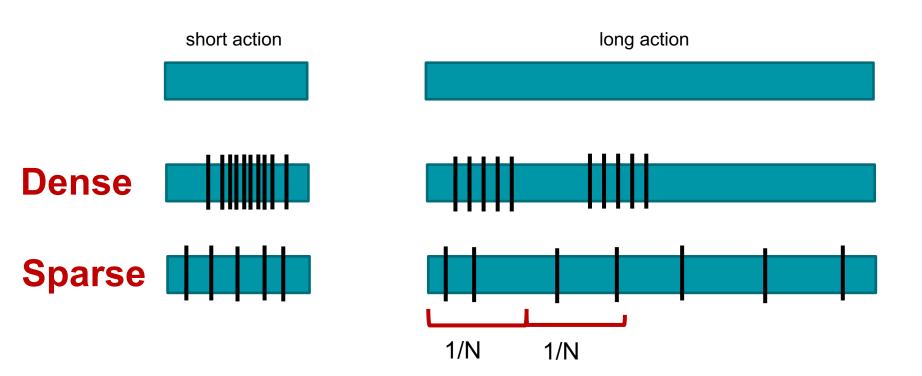




All models and methods
Sample frames...
Sampling is often hidden in
It is critical...



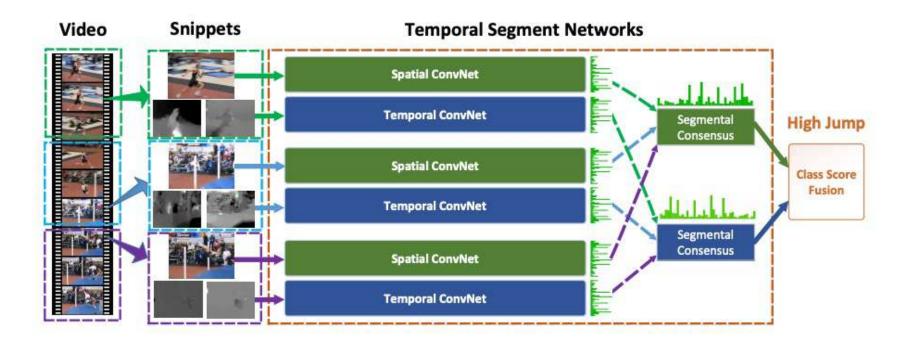
Two sampling approaches





Sparse sampling

Temporal Segment Networks (TSN) – Wang et al, ECCV 2016





Two sampling approaches

Dense

Better motion features

Short motion signature

Easier to implement

Better for cross-dataset generalisation

Sparse

More complex features

Complete action representation

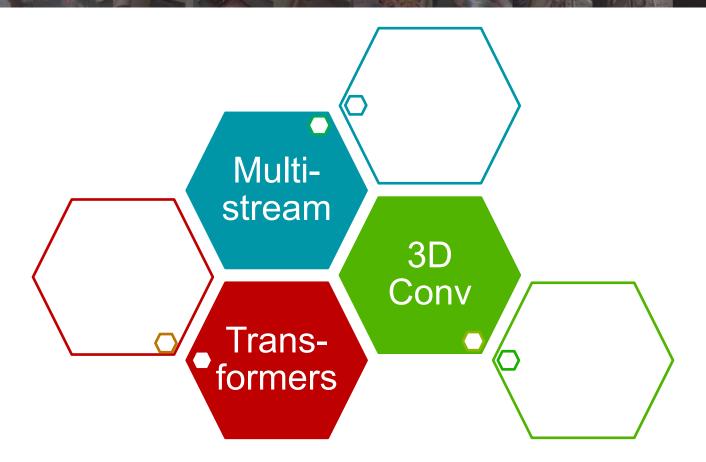
More augmentations

Better for temporal datasets

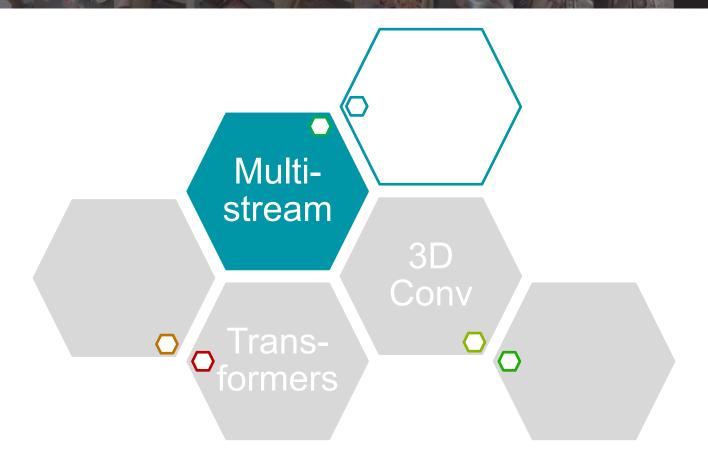


Models

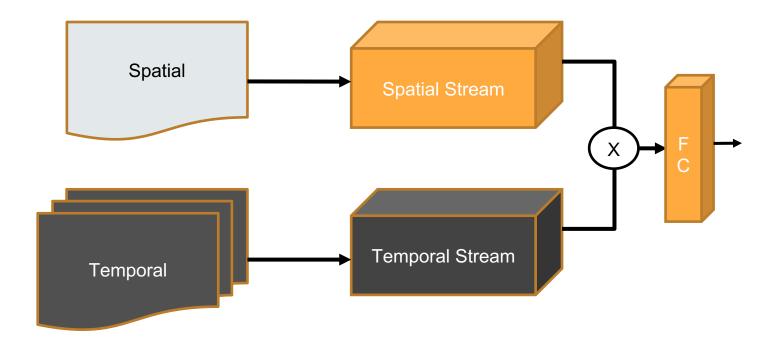




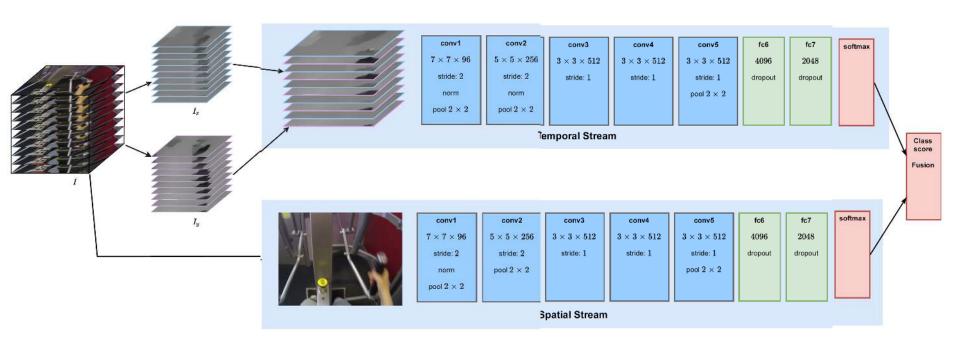




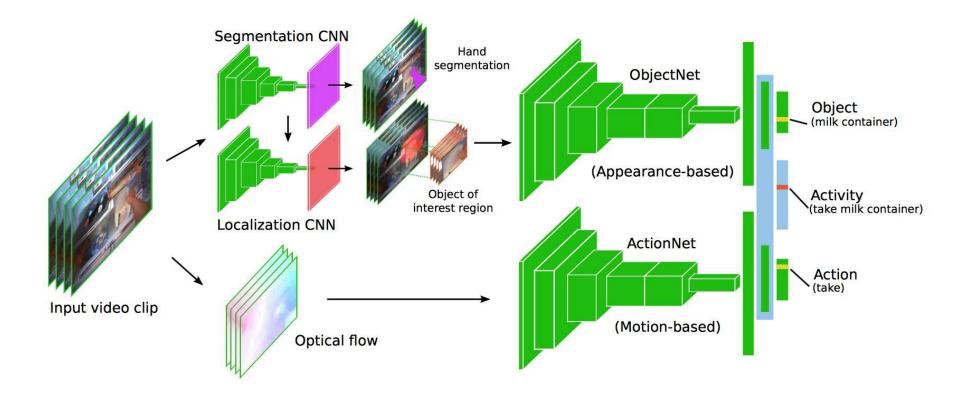




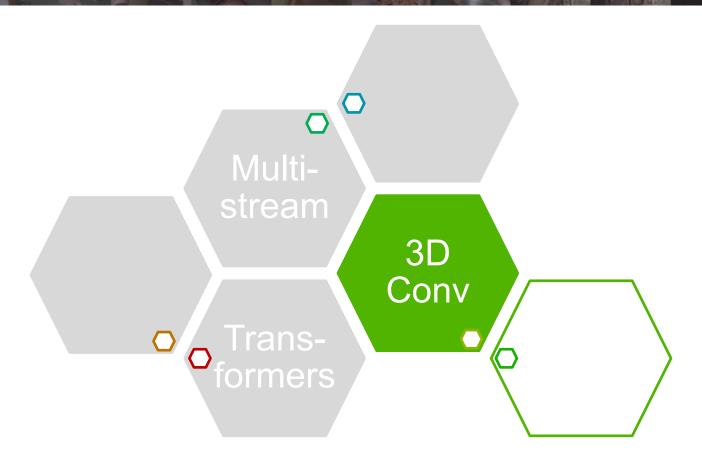






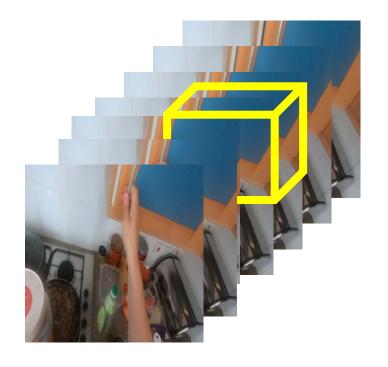


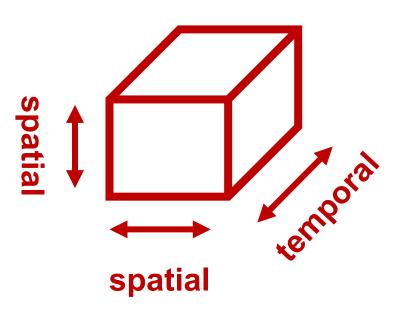






3D Convolutional







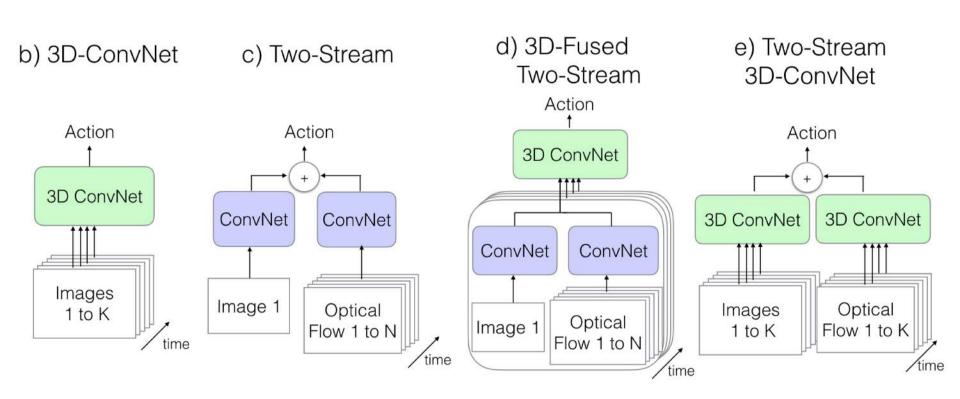
3D Convolutional

- Initial attempts required initialisation from 2D Networks (i.e. ImageNet)
 - No presence of large scale video dataset
 - Inflated networks (I3D) Carriera et al

The objective was to remove the need for optical flow...

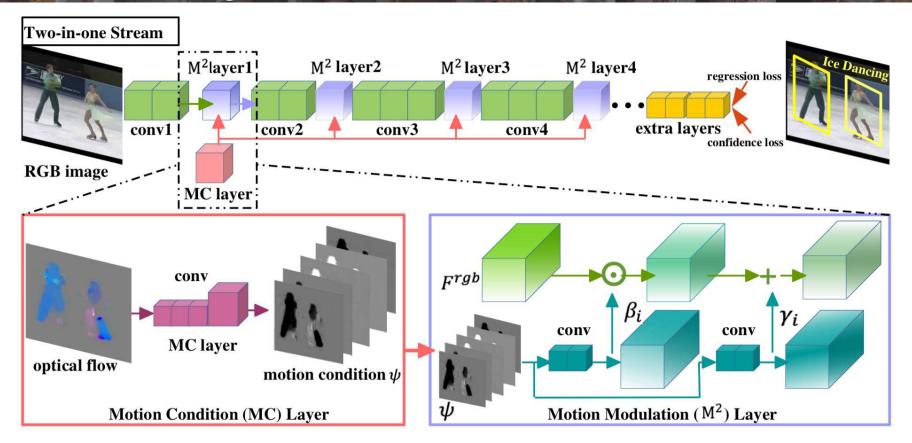


3D Convolutional

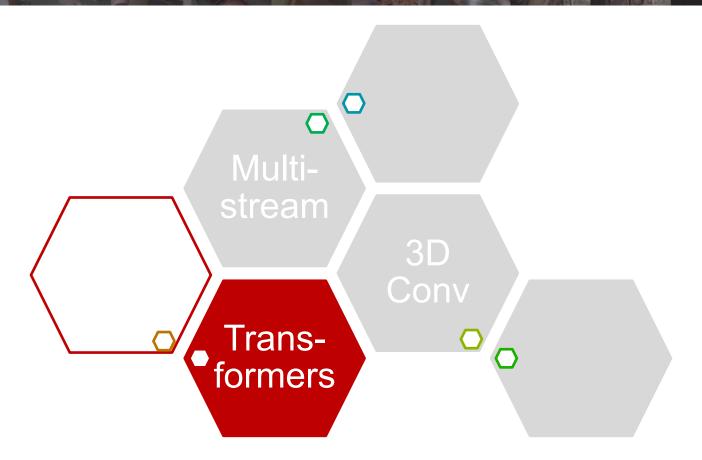




Via knowledge distillation



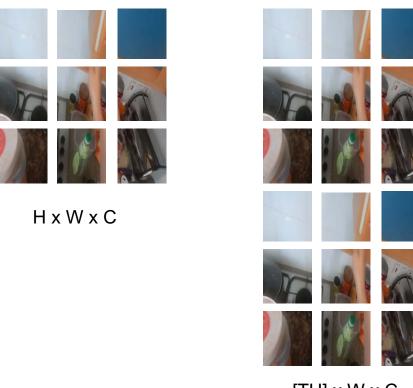






Vision Transformer (ViT) Class Bird MLP Ball Head Car Transformer Encoder Patch + Position Embedding 8 9 6 4 * Extra learnable Linear Projection of Flattened Patches [class] embedding



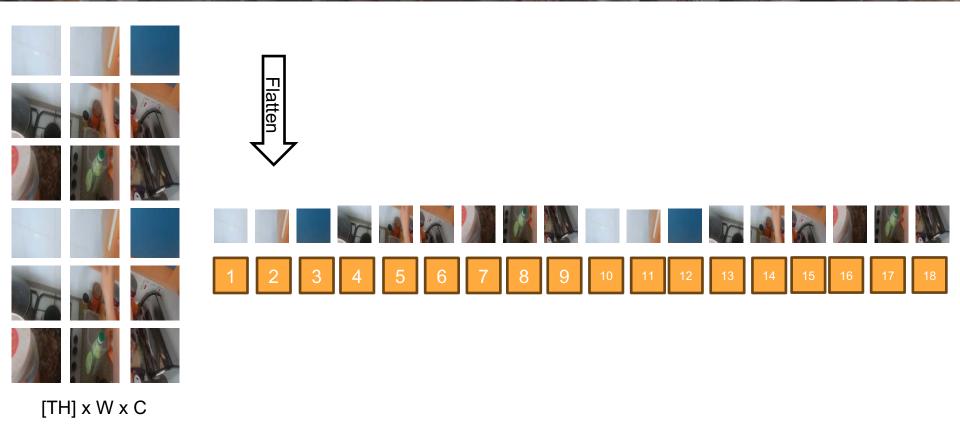




H x W x [CT]

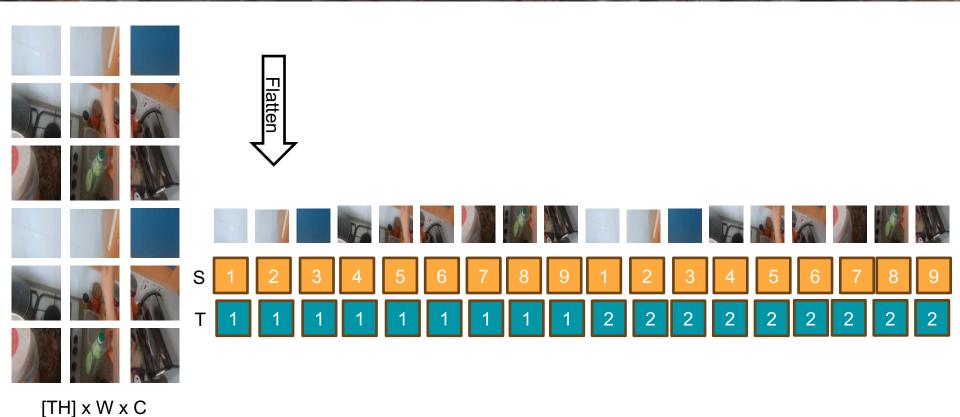




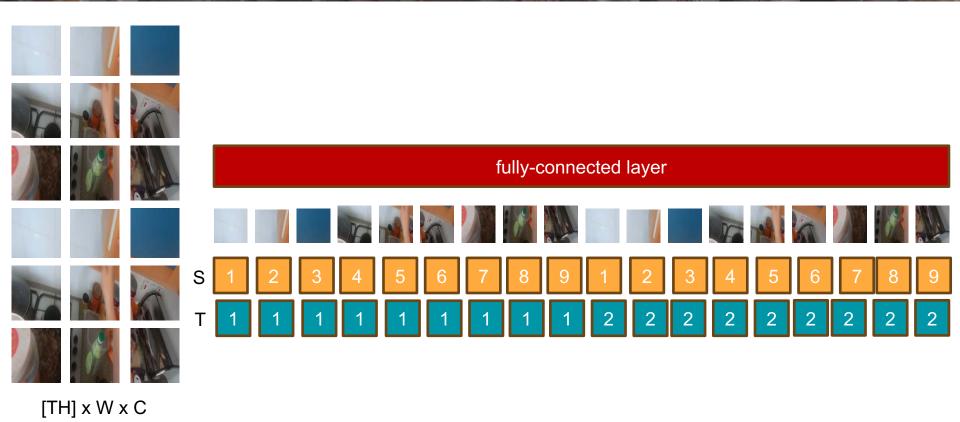




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TimeSFormer

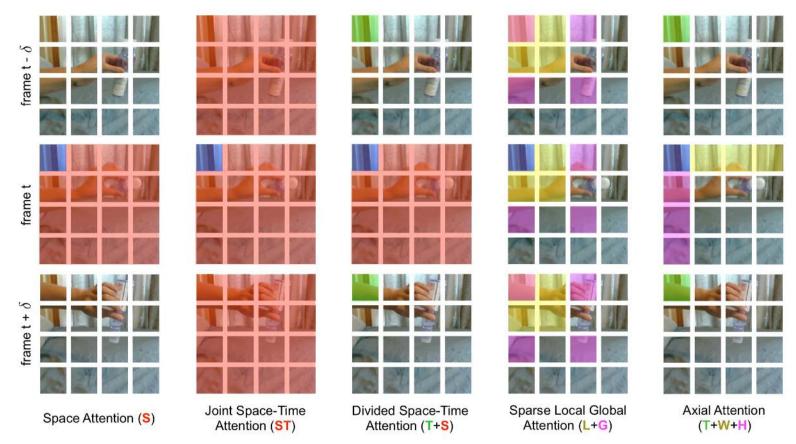




Figure from: Bertasius et al. Is Space-Time Attention All You Need for Video Understanding? ArXiv 2021

MotionFormer

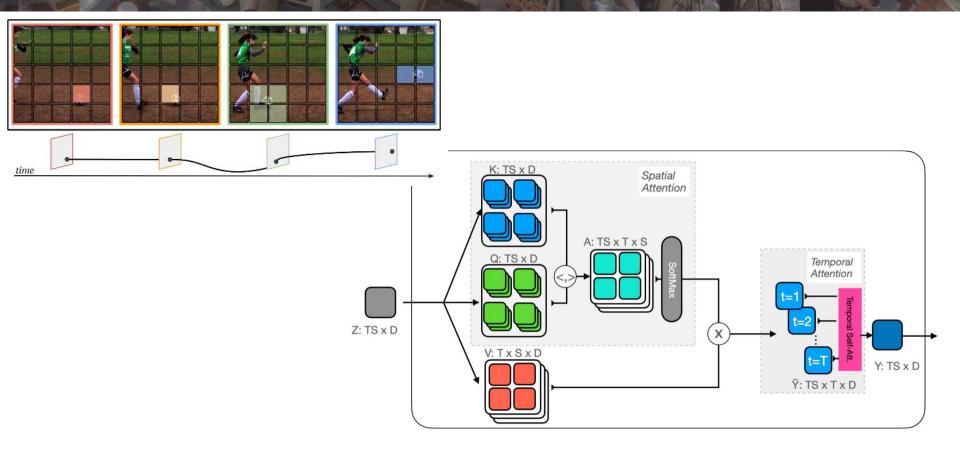
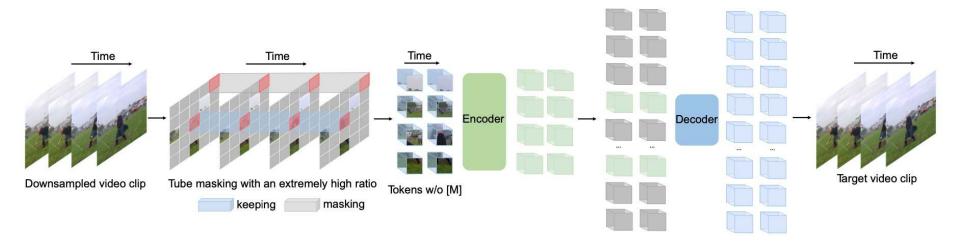




Figure from: Patrick et al. Keeping Your Eye on the Ball: Trajectory Attention in Video Transformers. NeurIPS 2021

VideoMAE





OmniVore

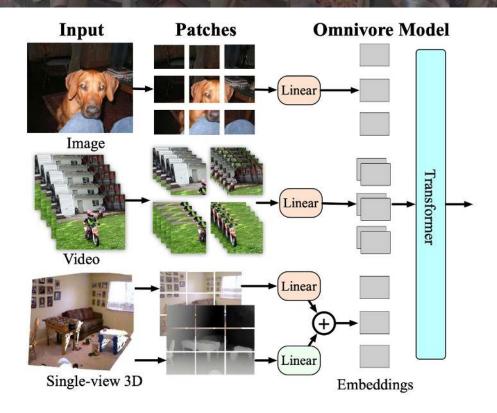
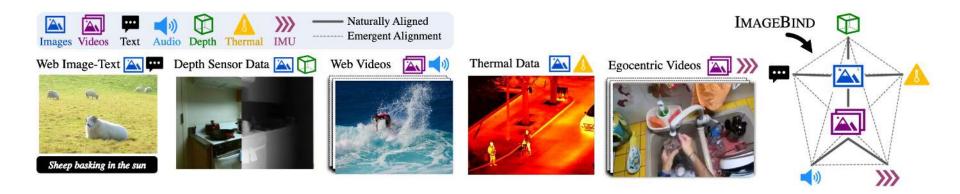


Figure 2. Multiple visual modalities in the OMNIVORE model.



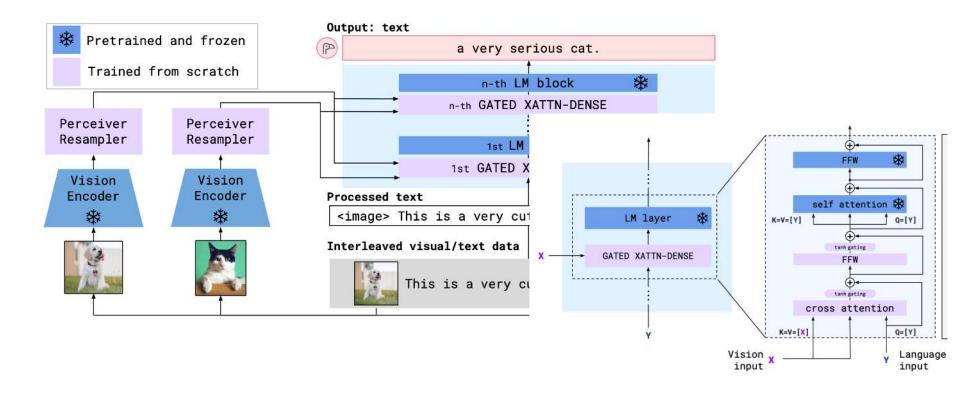
ImageBind



$$L_{\mathcal{I},\mathcal{M}} = -\log \frac{\exp(\mathbf{q}_i^{\mathsf{T}} \mathbf{k}_i / \tau)}{\exp(\mathbf{q}_i^{\mathsf{T}} \mathbf{k}_i / \tau) + \sum_{j \neq i} \exp(\mathbf{q}_i^{\mathsf{T}} \mathbf{k}_j / \tau)}$$



Flamingo





InternVideo

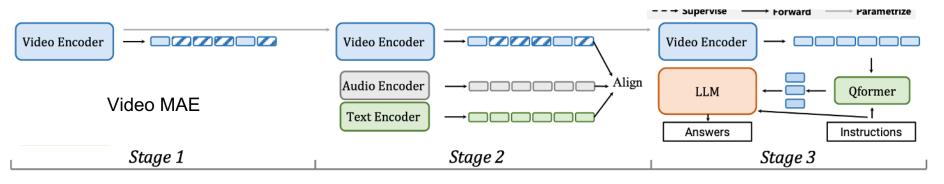


Figure 2: Framework of **InternVideo2**. It consists of three consecutive training phases: unmasked video token reconstruction, multimodal contrastive learning, and next token prediction. In stage 1, the video encoder is trained from scratch, while in stages 2 and 3, it is initialized from the version used in the previous stage.



InternVideo Supervise Forward Video Encoder Video Encoder Video Encoder Align Audio Encoder LLM Qformer Text Encod Answe Instructions ∕ge 1 **∠**age 3 Stage 2 Figu mework of InternVideo2, sts of three consecutive training unmasked video token nd next token prediction. In stage deo encoder is trained from on, multimodal contrastive le hile in stages 2 and 3, it is in from the version used in the prev





We are still lacking the right understanding



From Clip to Video

Video



Wash carrot



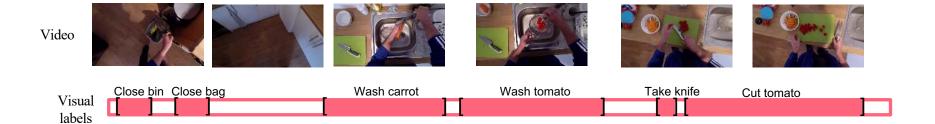
From Clip to Video



Wash carrot



From Clip to Video







Most models work only within context] lignoring the



Long-Term Feature Bank

Target frame







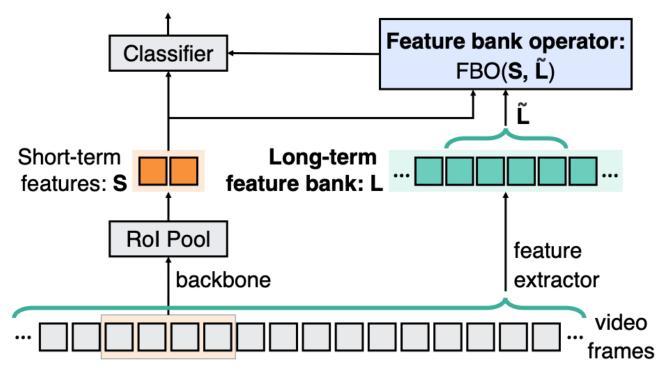


Input clip (4 seconds)

Figure 1. What are these people doing? Current 3D CNN video models operate on short clips spanning only \sim 4 seconds. Without observing longer-term context, recognition is difficult. (Video from the AVA dataset [14]; see next page for the answer.)



Long-Term Feature Bank



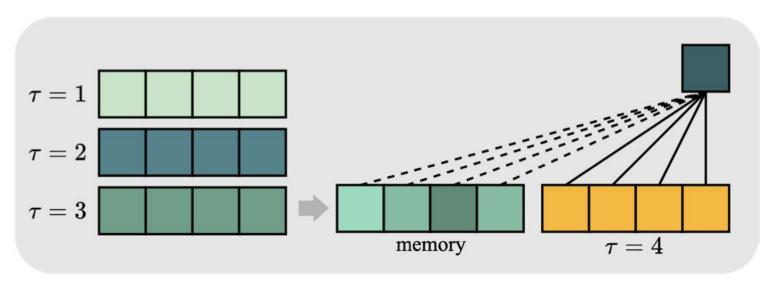
(b) 3D CNN with a Long-Term Feature Bank (Ours)



Memory Consolidation

self-attention

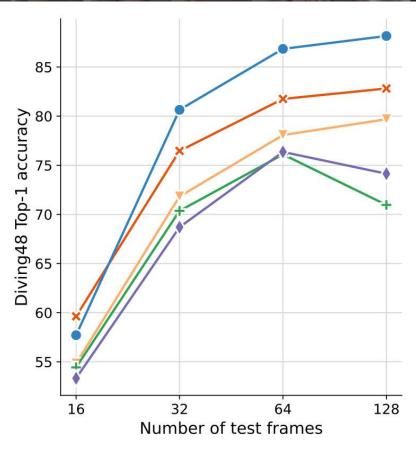
--- cross-attention



Memory-Consolidated ViT



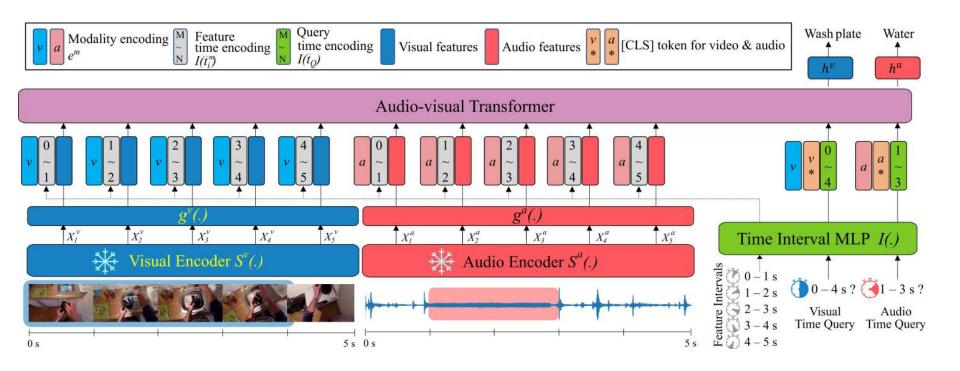
Memory Consolidation





TIM: A Time-Interval Audio-Visual Machine

with: Jacob Chalk* Jaesung Huh* Vangelis Kazakos Andrew Zisserman







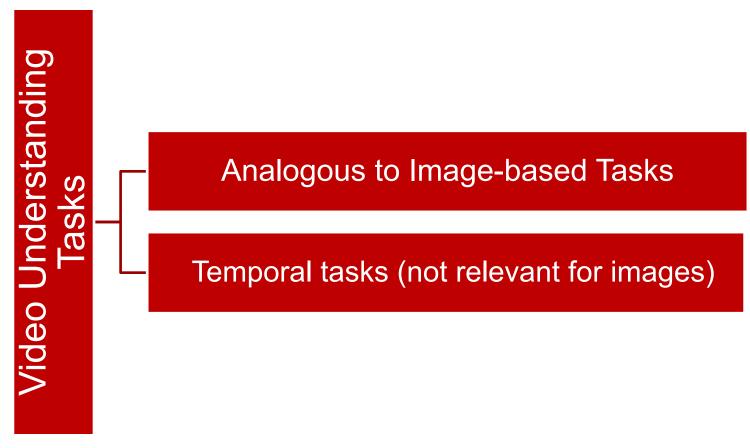
Do you think video is a modality?!!



On Tasks...



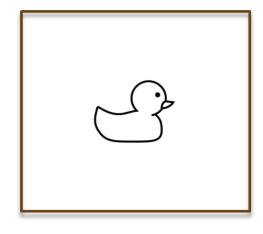
Two types of video understanding tasks





Image

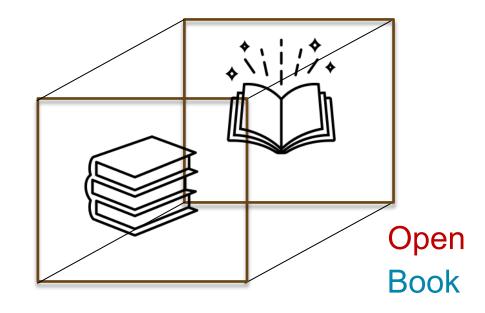
Object Recognition



Duck

Video

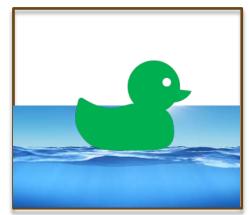
Action Recognition





Image

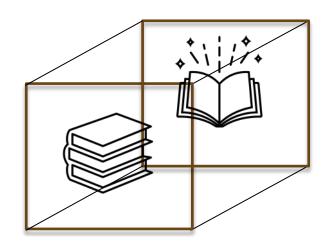
Image Captioning



A green duck swimming In clear water

Video

Video Captioning

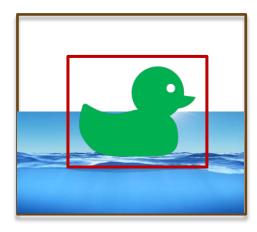


A book picked from top of the pile and opened to a page in the middle



Image

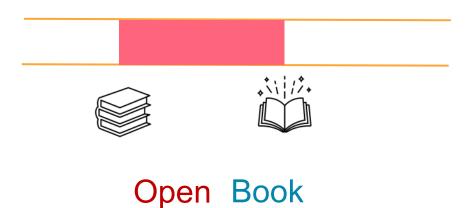
Object Detection



Duck

Video

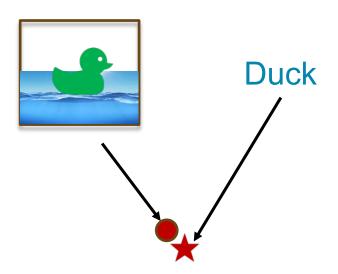
Action Detection





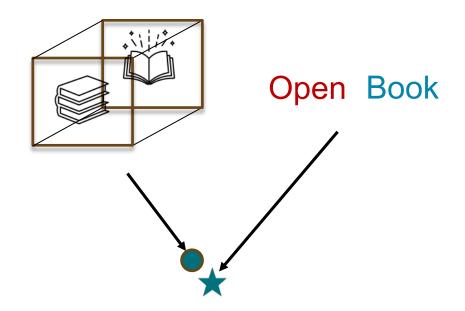
Image

Image Retrieval



Video

Video Retrieval





What is a Cross-Modal Video Retrieval?

Video-to-Text Retrieval Task Ranked Text – Gallery (or Retrieval Set) put garlic down



Q put garlic down



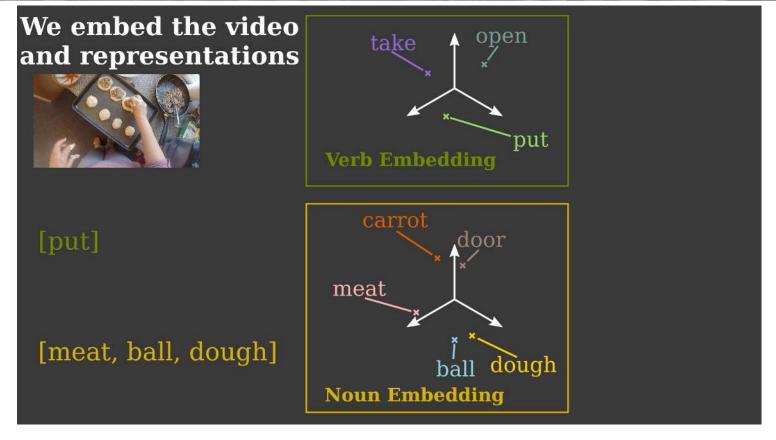


In this work we focus on **Fine-Grained Action Retrieval**

I put meat on a ball of dough

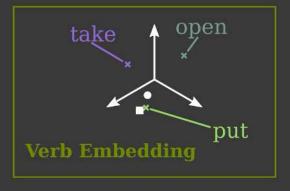


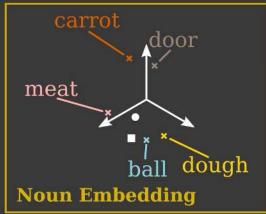




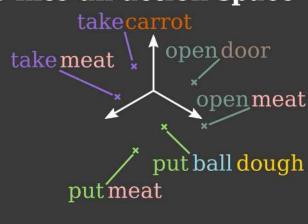


Fine-Grained Action Retrieval



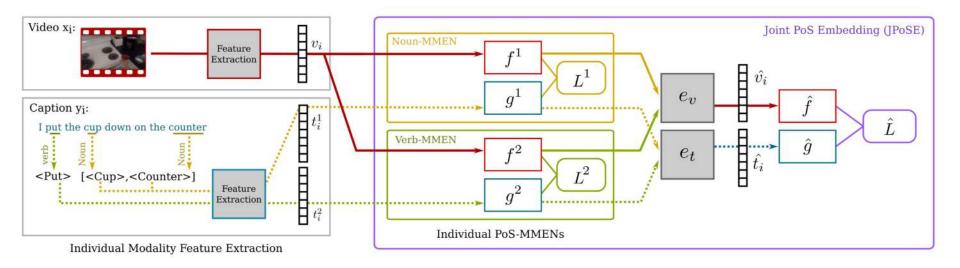








Fine-Grained Action Retrieval





with: Michael Wray Gabriela Csurka Diane Larlus

Maximum activation examples for a neuron in a noun PoS Embedding (Cutting Board) - Figure 4





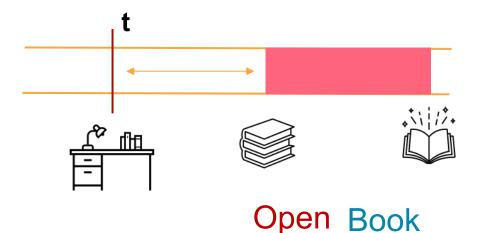
Non-Analogous Tasks

Image



Video

Action AnticipationWhat will happen after 1 second?





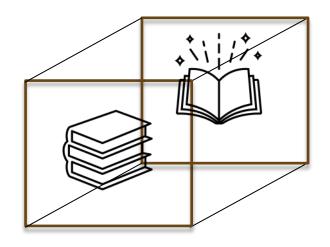
Non-Analogous Tasks

Image



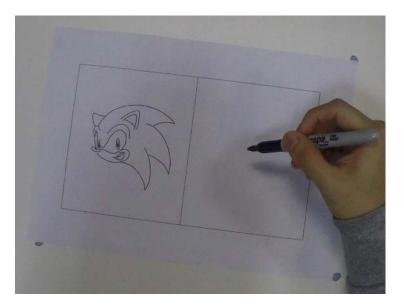
Video

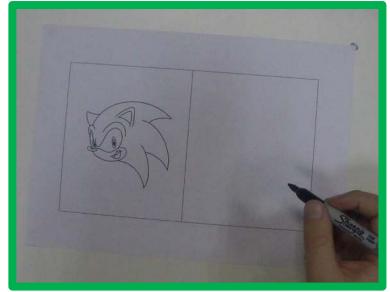
Skill UnderstandingHow did you open the book?

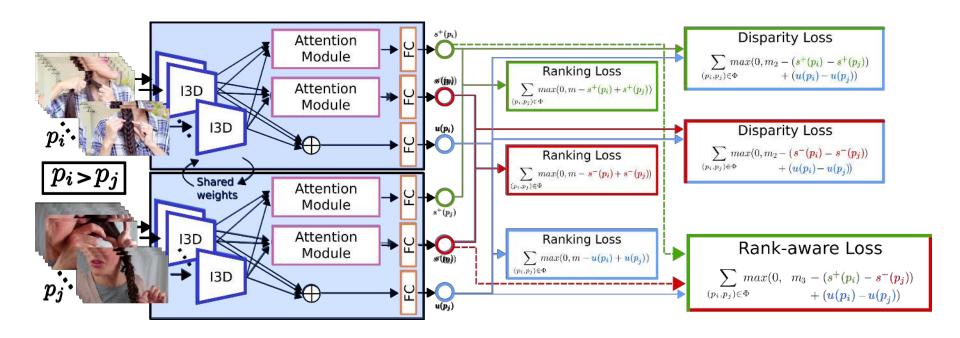




Pairwise annotations of videos, indicating higher skill or no skill preference









Low-skill Attention Module

Surgery

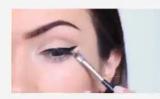


























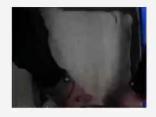


High-skill Attention Module

Dough









Origami

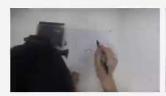






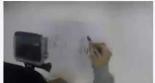














Analogous Tasks

Image

Object Counting



Video

Action Counting



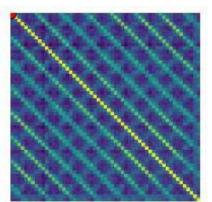


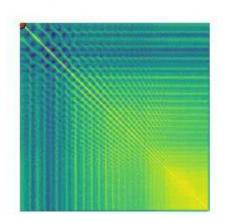
Countix

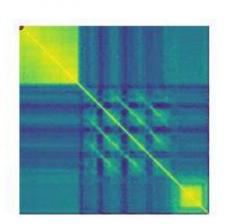








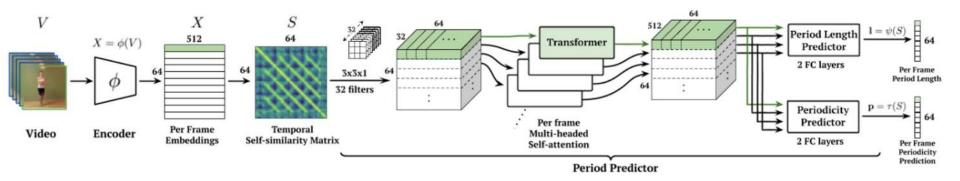






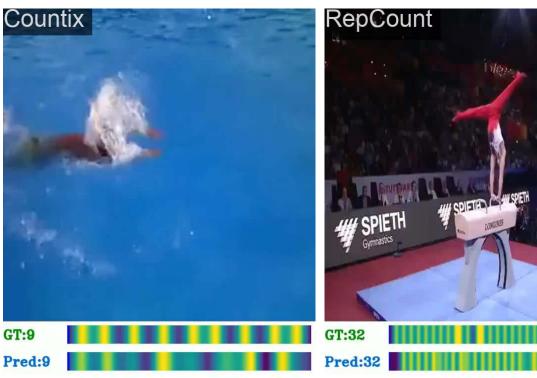
Dima Damen July 26, 2024

Countix

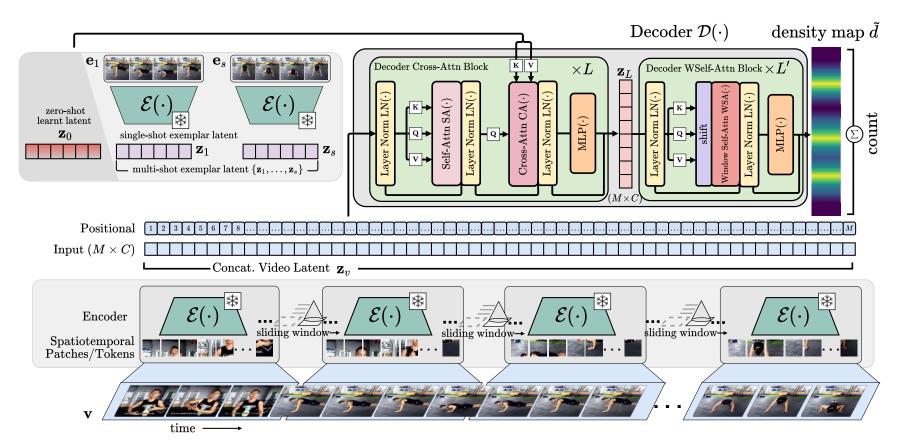














(a)	RepCount
\ /	

Method	Encoder	$RMSE\downarrow$	$MAE \downarrow$	OBZ↑	OBO↑
RepNet [15]	R2D50	_	0.995	-	0.013
TransRAC [18]	VSwinT	9.130*	0.443	0.085^*	0.291
MFL [27]†	VSwinT	2 - -8	0.384	1.—1	0.386
ESCounts	VSwinT	6.905	0.298	0.183	0.403
ESCounts	VMAE	4.455	0.213	0.245	0.563

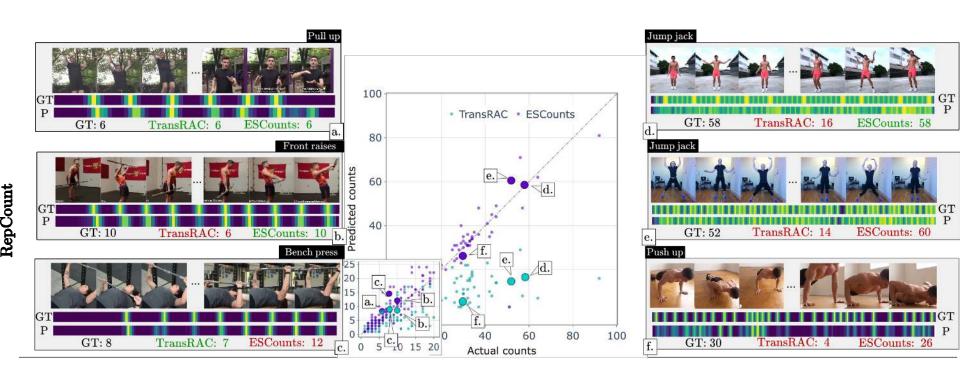
(c) UCFRep

Method	Encoder	$RMSE\downarrow$. MAE↓	OBZ↑	OBO↑
Levy & Wolf [25]	RX3D101	-	0.286	8 - 0	0.680
RepNet [15]	R2D50	=	0.998	-	0.009
Context (F) [62]	RX3D101	5.761*	0.653^{*}	0.143^{*}	0.372*
TransRAC [18]	VSwinT	=	0.640	-	0.324
MFL [27]†	RX3D101	-	0.388	-	0.510
ESCounts	RX3D101	2.004	0.247	0.343	0.731
ESCounts	VMAE	1.972	0.216	0.381	0.704

(b) Countix

Method	Encoder	$RMSE \downarrow$	MAE↓	OBZ↑	OBO↑
RepNet [15]	R2D50	-	0.364	-	0.697
Sight & Sound [64]†	R(2+1)D18	=	0.307	-	0.511
ESCounts	R(2+1)D18	3.536	0.293	0.286	0.701
ESCounts	VMAE	3.029	0.276	0.319	0.673







Analogous Tasks

Image

Text-to-image Generation



Stable Diffusion

Video

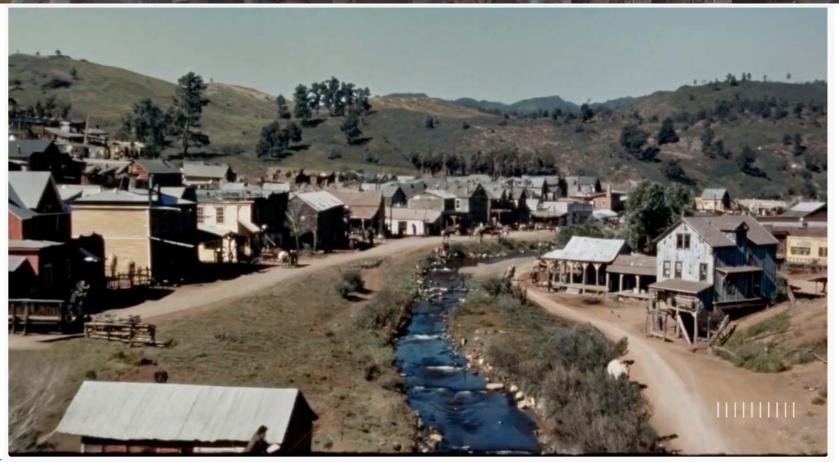
Text-to-Video Generation



SORA



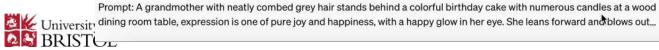
Text-to-Video Generation



n 232

Text-to-Video Generation





Dima Damen 233 July 26, 2024



Generative Video approaches do not yet or action consequences...





GenHowTo: Learning to Generate Actions and State Transformations from Instructional Videos







Dima Damen



Michael Wray



Ivan Laptev



Josef Šivic

















♠ smoothie in a blender







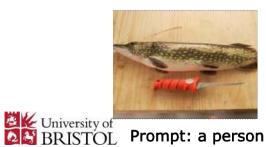




Prompt: a frosted cake with strawberries around the top



Prompt: a person kneading dough on a cutting board







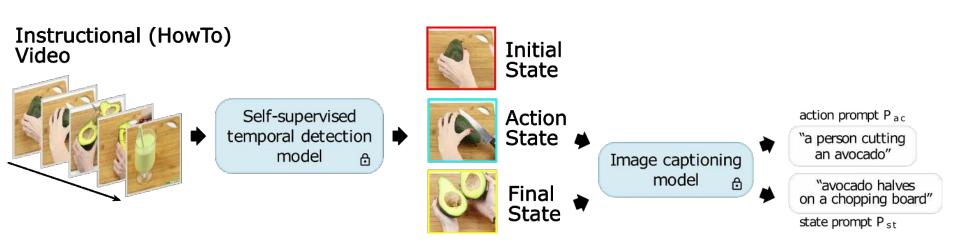


Prompt: a person cutting a fish on a cutting board

Two contributions.... Dataset & Method



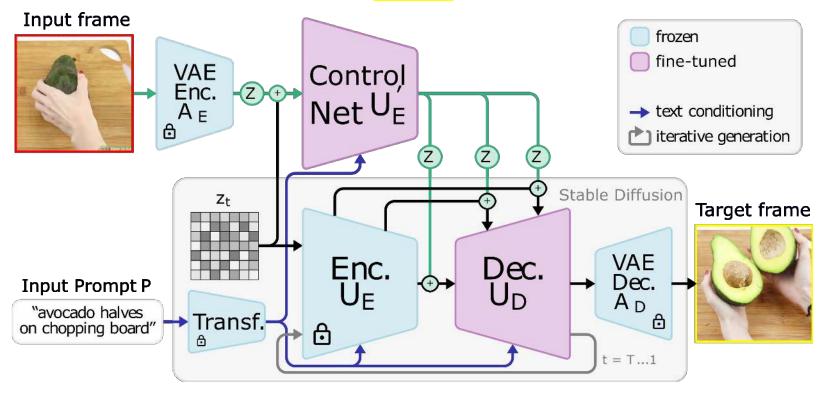
Two contributions.... Dataset & Method



Tomas Soucek, Jean-Baptiste Alayrac, Antoine Miech, Ivan Laptev, and Josef Sivic (2022). Multi-task learning of object state changes from uncurated videos.



Two contributions.... Dataset & Method





with: Tomas Soucek Ivan Laptev Michael Wray Josef Sivic





T Soucek et al (2023). GenHowTo: Learning to Generate Actions and State Transformations from Instructional Videos. ArXiv

- Qualitative Evaluation...
 - Initial vs Final State
 - Binary Classifier

e <u>-</u>	Method	$Acc_{ac} \uparrow$	$Acc_{st} \uparrow$
	test set categories unseen	during trai	ning
(a)	Stable Diffusion	0.51	0.50
(b)	Edit Friendly DDPM	0.60	0.61
(c)	InstructPix2Pix	0.55	0.63
(d)	CLIP (manual prompts)	0.52	0.62
(e)	GenHowTo	0.66	0.74
	test set categories seen d	uring train	ing
(f)	Edit Friendly DDPM [†]	0.69	0.80
(g)	GenHowTo [†]	0.77	0.88
(h)	Real images	0.96	0.97

[†] Models trained also on the test set *categories*.



a person is wrapping a tortilla on a plate



REAL IMAGE GENERATED

a man pouring beer into a glass



REAL IMAGE GENERATED



a man sitting at a table holding a glass of beer

REAL IMAGE GENERATED



a plate with two burritos on it





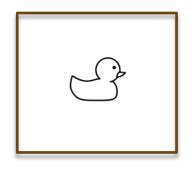
It is more important to understand consequences of actions that to generate



Analogous Tasks

Image

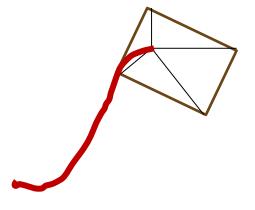
Image − to − 3D





Video

• Video – to - 3D

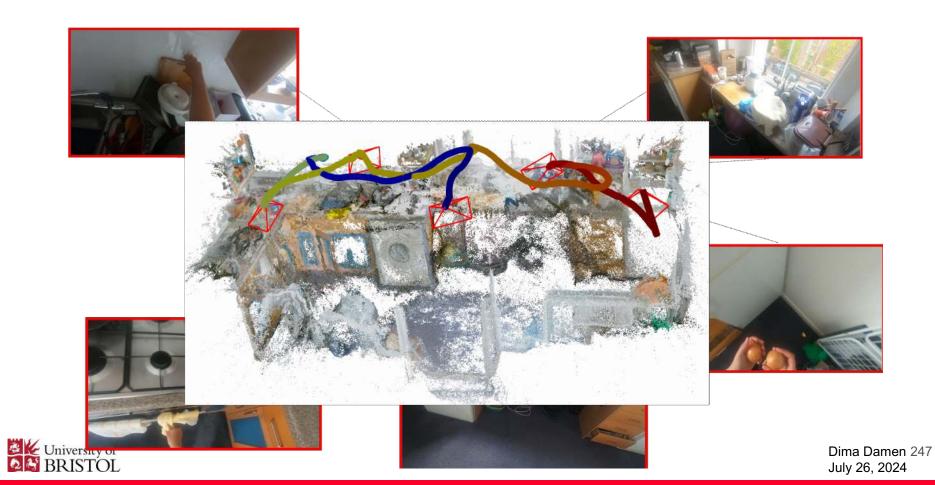






Almost all video-to-3D static scene







Out of Sight, Not Out of Mind

Chiara Plizzari

Shubham Goel

Toby Perrett

Jacob Chalk

Angjoo Kanazawa

Dima Damen

http://dimadamen.github.io/OSNOM

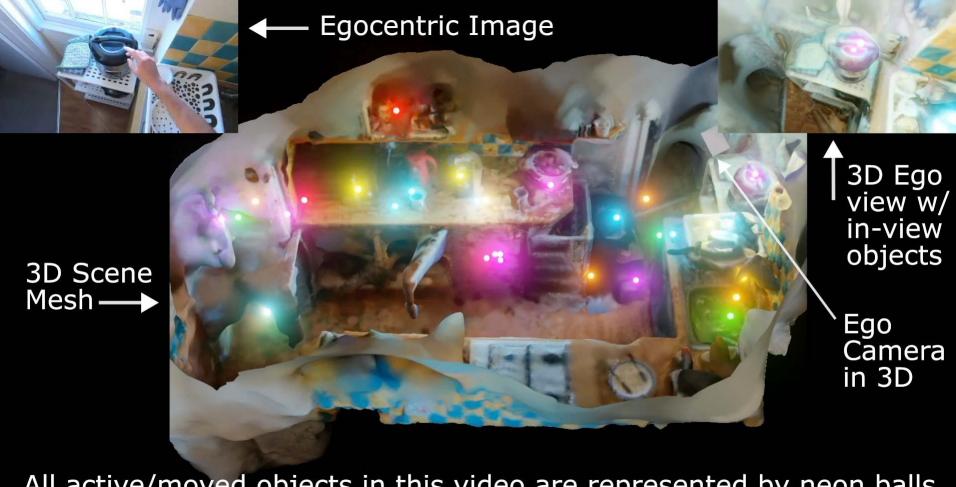








All active/moved objects in this video are represented by neon balls. Their initial positions are shown at the start of the video



All active/moved objects in this video are represented by neon balls. Their initial positions are shown at the start of the video

Non-Analogous Tasks

Image



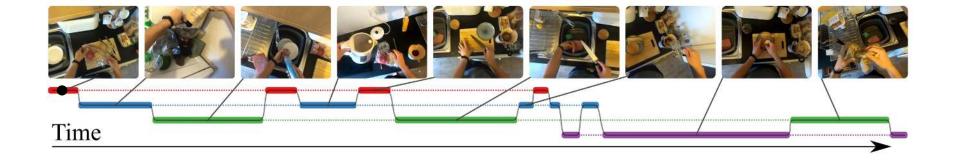
Video

 Understanding Goals in Long Videos

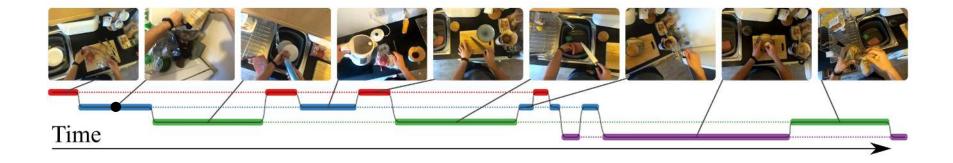




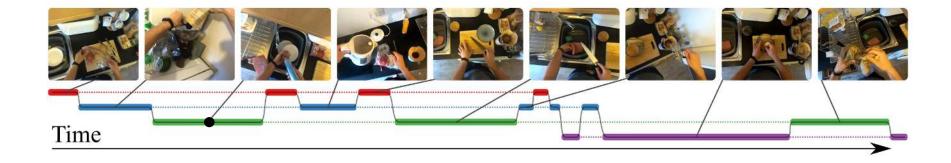
Goals...



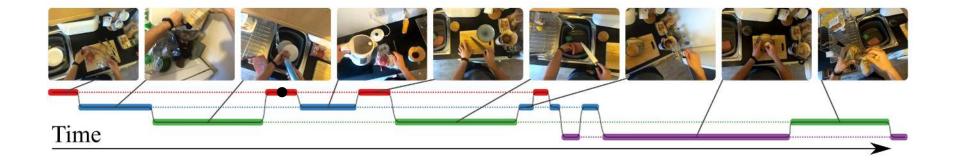




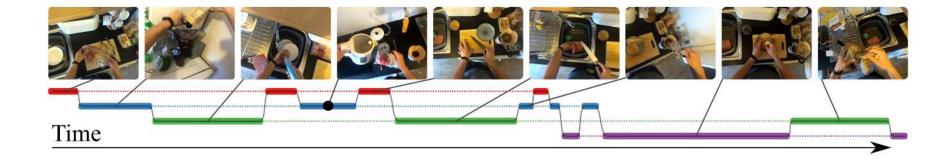




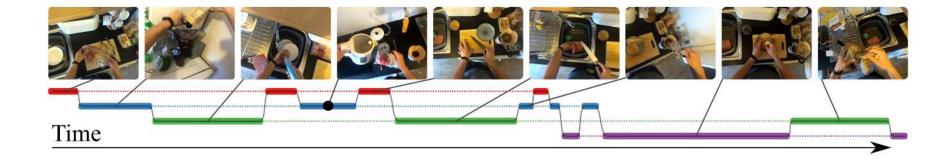
















Thread Bank



Thread Bank



...............

UnweaveNet

Thread Bank





...............

...........







...........





...........

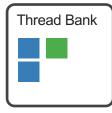






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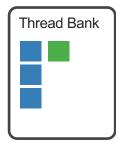






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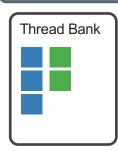






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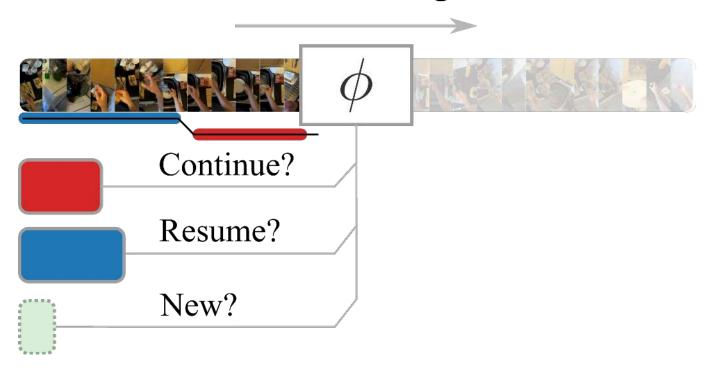
UnweaveNet



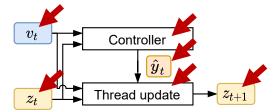




Unweaving

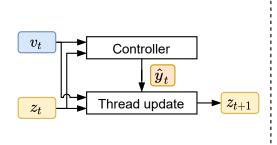




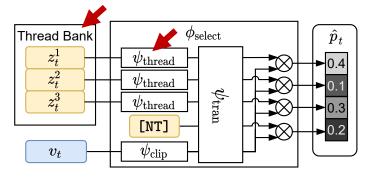


(a) UnweaveNet Overview





(a) UnweaveNet Overview

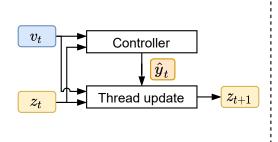


(b) Controller Architecture

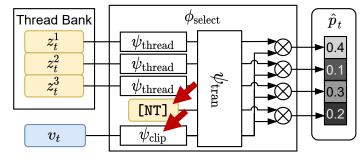
Two learnt embeddings

$$\psi_{\mathrm{thread}} : \mathbb{R}^D \to \mathbb{R}^E$$





(a) UnweaveNet Overview



(b) Controller Architecture

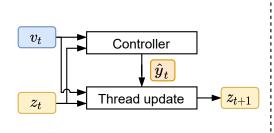
Two learnt embeddings

$$\psi_{\text{thread}} : \mathbb{R}^D \to \mathbb{R}^E$$

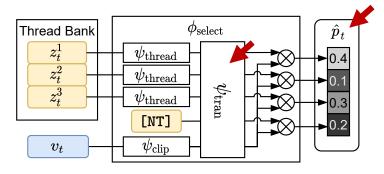
$$\psi_{\text{clip}}: \mathbb{R}^C \to \mathbb{R}^E$$

Learnt Encoding $[\mathtt{NT}] \in \mathbb{R}^{3}$



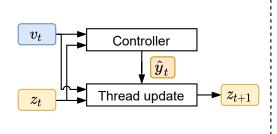


(a) UnweaveNet Overview

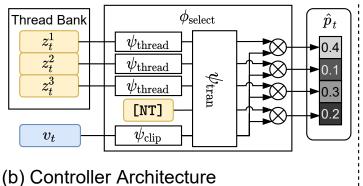


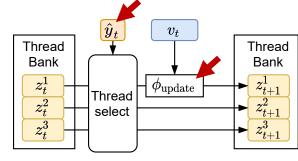
(b) Controller Architecture



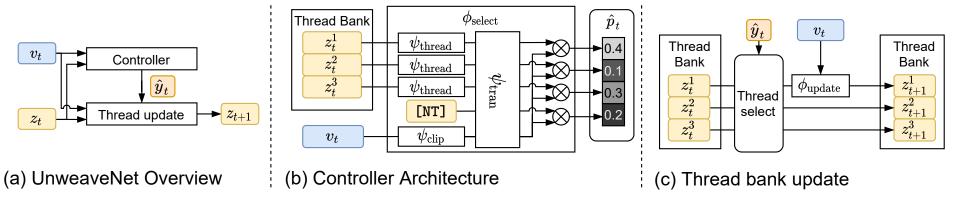


(a) UnweaveNet Overview





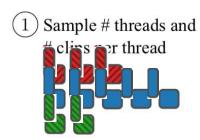
(c) Thread bank update



- Trained end-to-end including the backbone for clip features
- decisions made by $\phi_{
 m select}$ are supervised using **teacher forcing**
 - o at each time step, z_t is populated according to the ground-truth assignments $y_{1:t-1}$
 - A loss is then imposed on the output p_t given the correct decision y_t with focal hyperparameter γ due to the imbalance in decisions



 We propose self-supervised pretraining for UnweaveNet that samples threads from different parts of a long video and synthetically forms woven activity stories.





 We propose self-supervised pretraining for UnweaveNet that samples threads from different parts of a long video and synthetically forms woven activity stories.

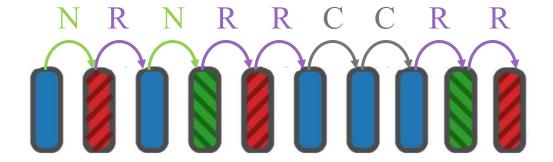
1 Sample # threads and # clips per thread



2) Position threads' clips within video



1000s of synthetic stories from training set.





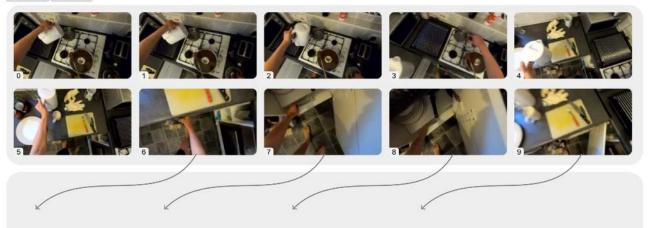
Labelled Sequences

Story Annotator

Story ID: c7c7f261-e5c7-4641-b0cf-b2b4e8c8ef3d Video ID: P06_103 Start time: 7567

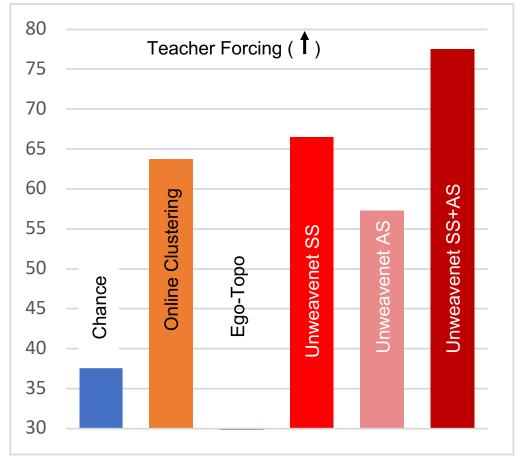
Splits: train+val

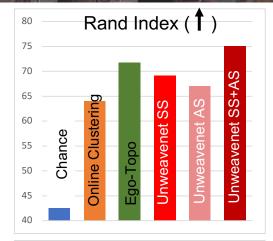
Skip (space) Next (enter)

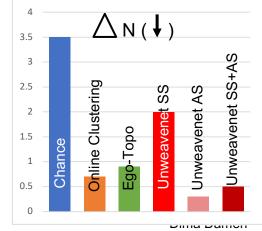


Split	# Threads		
	1	2	3
Train	718	201	32
Val	211	94	46
Test	50	50	50
Total	979	345	128

Table 1. EPIC-KITCHENS activity-story dataset by # of threads.







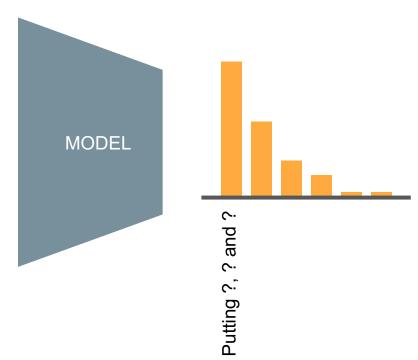


VU - An Egocentric Perspective

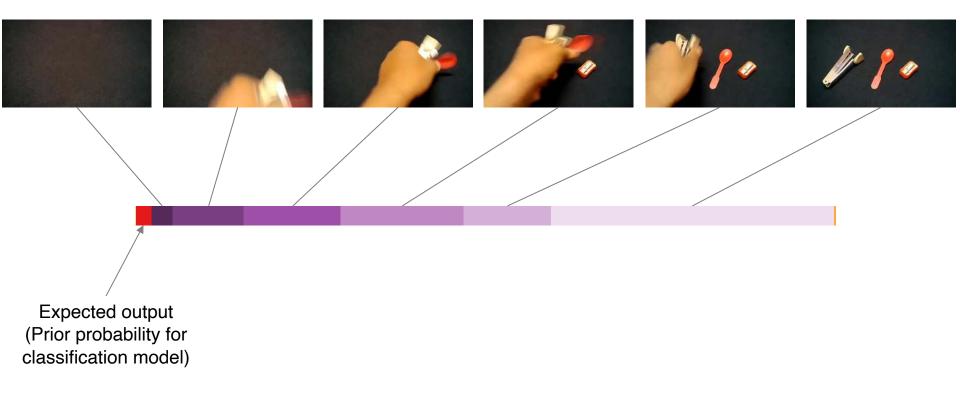




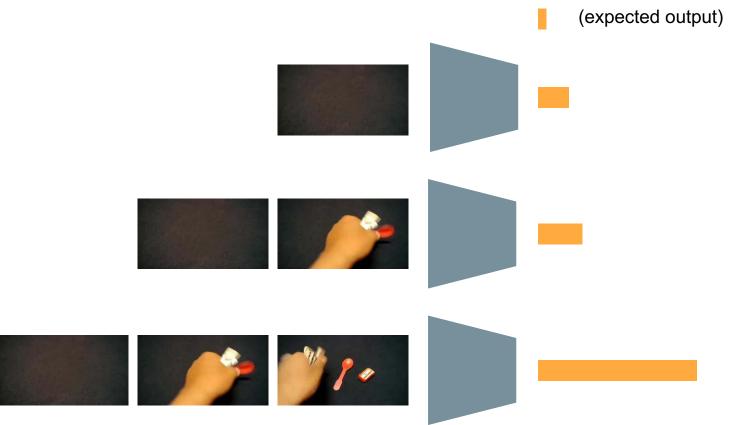




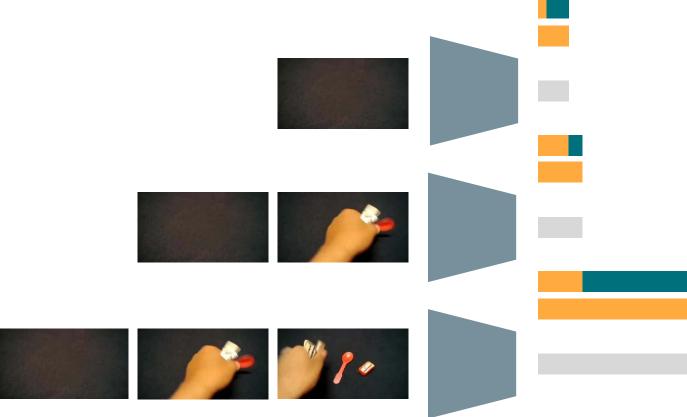
































































$$\Delta_3(\{1,2,4,5\}) = -.2$$



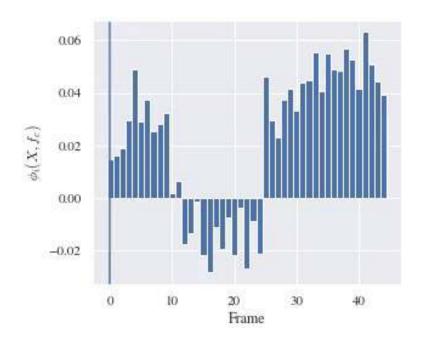




MODEL



Frame Attributions in Video Models



Showing that something is empty



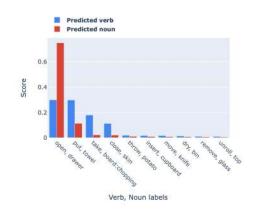


Frame Attributions in Video Models

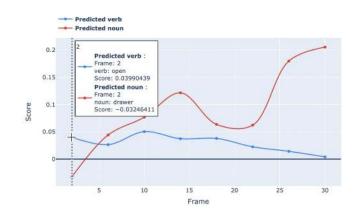
ESVs Dashboard for Epic



Model Predictions



ESV Predictions



Original Video:



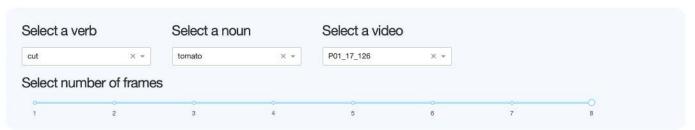


Selected Verb: 3, Selected Noun: 8, Video P01_103_84

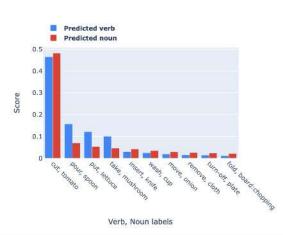


Frame Attributions in Video Models

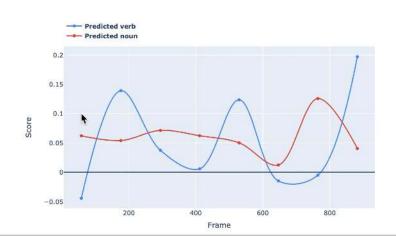
ESVs Dashboard for Epic



Model Predictions



ESV Predictions

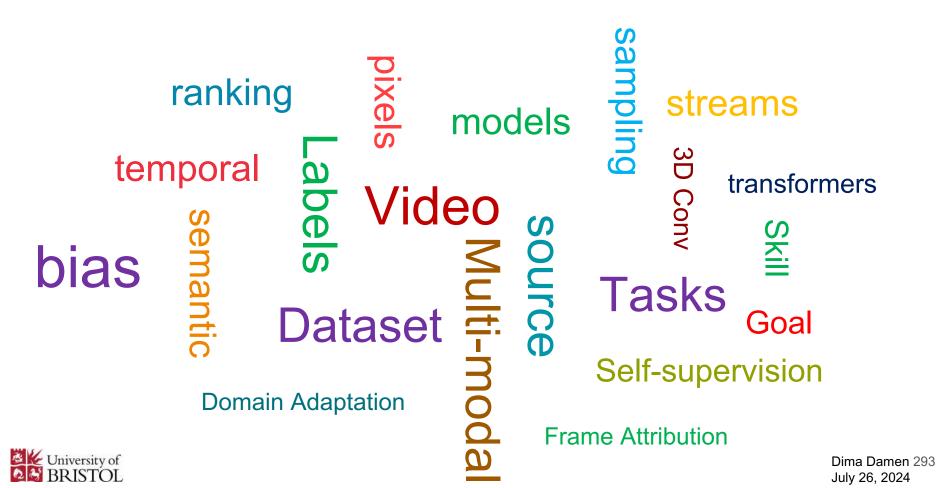


Original Video:



Selected Verb: 7, Selected Noun; 43, Video P01 17 126

Summary Wordle



and many more...





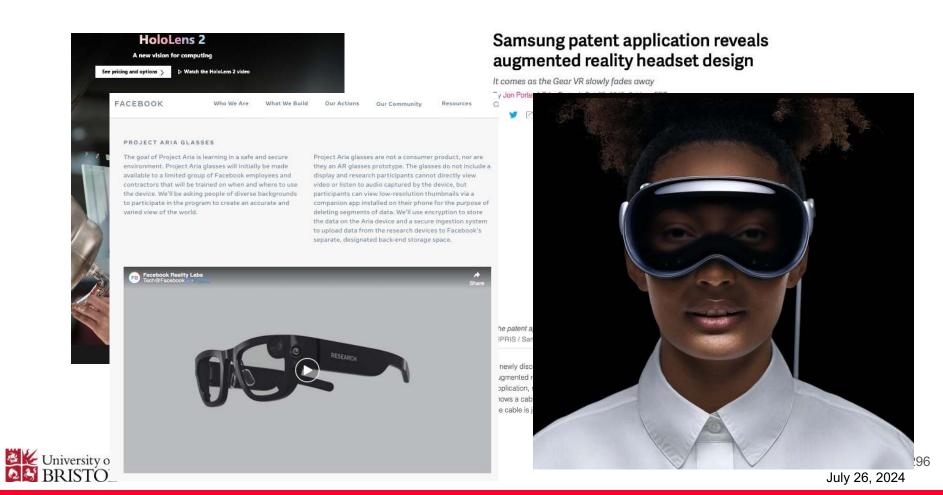


Video Understanding

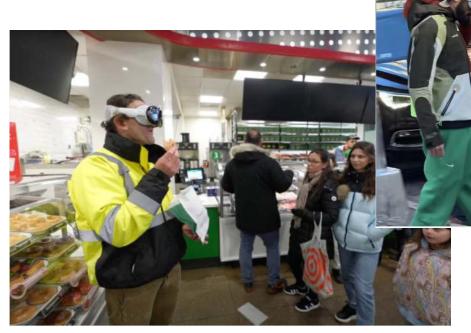
An Egocentric Perspective



The future is here...



The future is here...







Dima Damen July 26, 2024

Let's start with a show of hands...



Hands-Up if you are ready to wear a head-mounted or glass-mounted camera...



Hands-Up if this is NOT the future...



A world of isolated individuals....



Dangerous for crossing the road...



Mind-altering...



45 years ago...

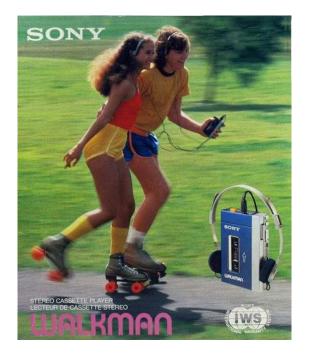




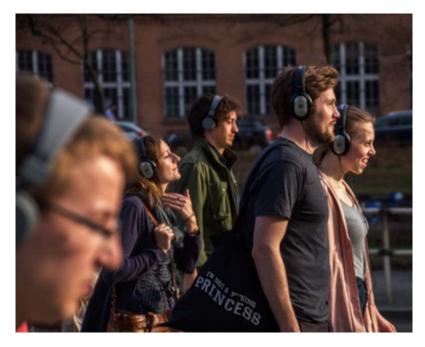


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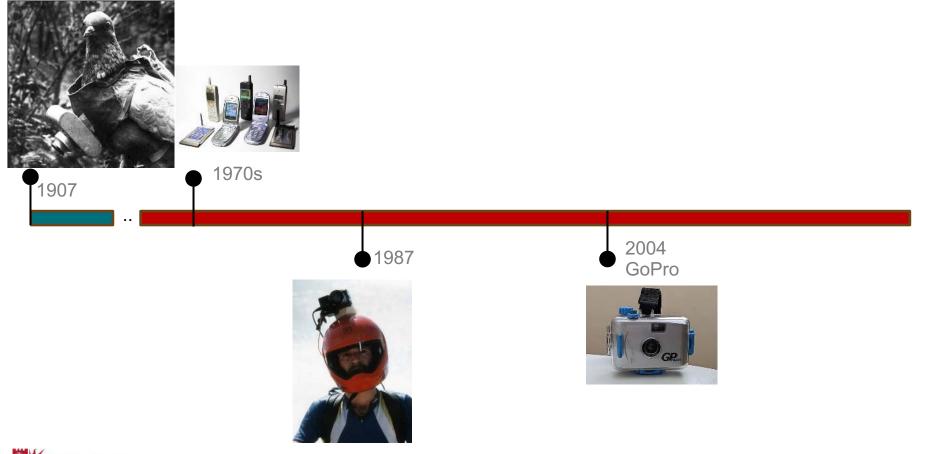
45 years ago...







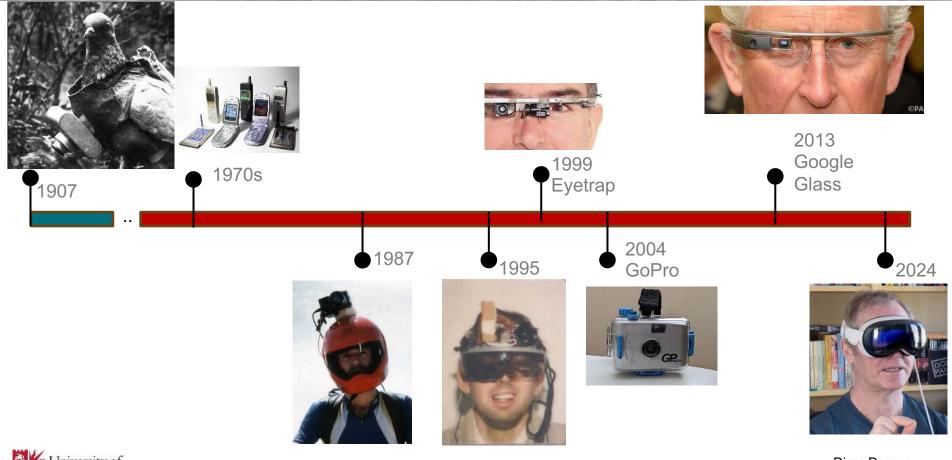










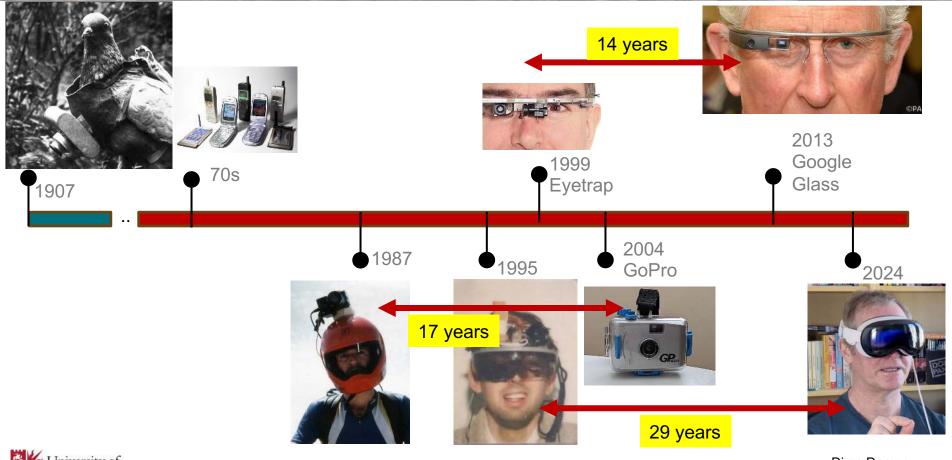


Dima Damen
BRISTOL

Dima Damen
July 26, 2024









Dima Damen July 26, 2024

How did we get here? a for GoPro-style camera on Can Apple Rescue the Vision Pro? Motorcyclist fights fi The \$3,500 "spatial computing" device has gathered dust on my Lost a landmark THE SHIFT Home > Biz > News shelf. Can tweaks and upgrades save it from obsolescence? helmet How Much Could A MOTORCYCLIST who was fined for having? 留 Share full article 会 口 口 106 the Way People (© 2 min read September 16, 2015 - 1:F Rebekah Cavanagh Listen to this article . 7:48 min Learn more le Google's new camera-embedded e₃ ▼ entertainment, raise privacy question By Kevin Kelleher 2024 Apple's \$3,500 first-generation Vision Pro is going for as little as \$2,500 on resale Undated: GoPro HD Motorsport Hero camera - motorbike / motorcycle helmet mounted websites. Clara Mokri for The New York Times Univers Dima Damen

July 26, 2024

An Outlook into the

Future of Egocentric Vision

Chiara Plizzari*, Gabriele Goletto*, Antonino Furnari*, Siddhant Bansal*, Francesco Ragusa*, Giovanni Maria Farinella†, Dima Damen†, Tatiana







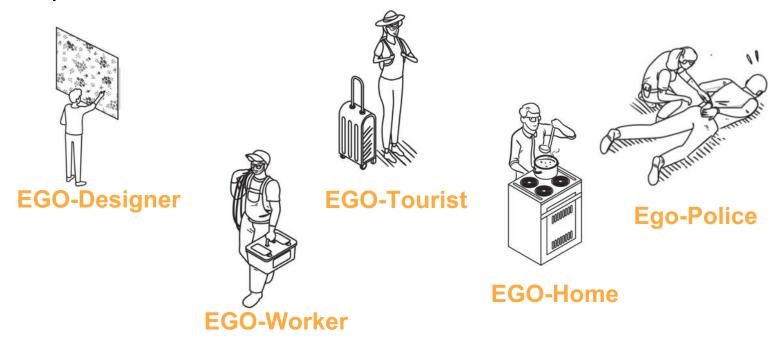


Envisioning an Ambitious Future and **Analysing** the Current Status of Egocentric Vision

How did we do this?

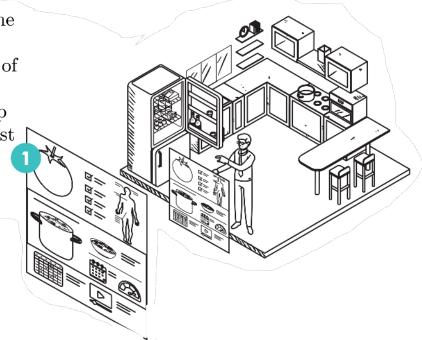


We imagined a device – *EgoAl* and envisioned its utility in multiple scenarios

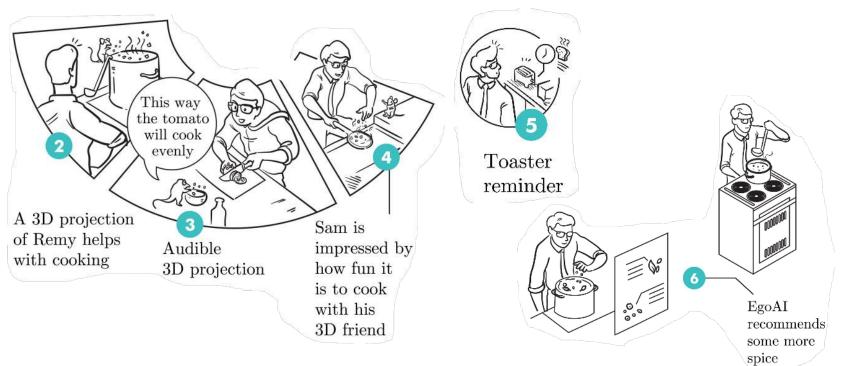


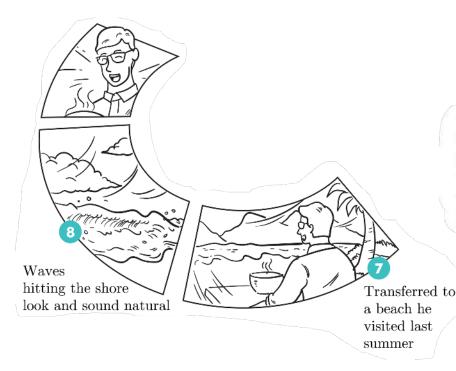


Sam is finally home after a long day.
EgoAI kept track of Sam's food intake and a tomato soup sounds like the best complementary nutrition





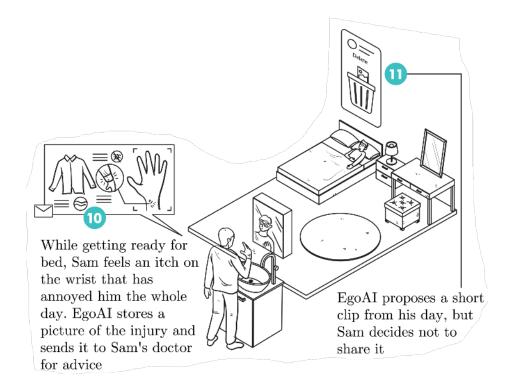




After dinner, Sam enjoys a group card game with his friends, who are connected through their own EgoAI



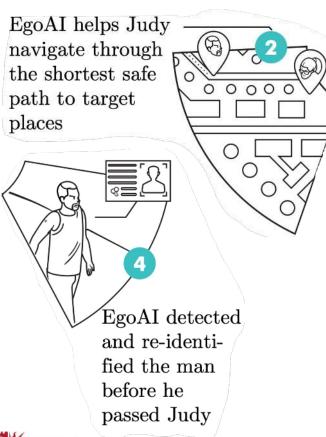






From Stories to Tasks

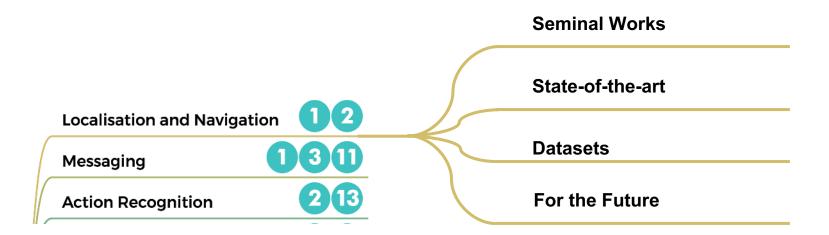
with: Chiara Plizzari, Gabriele Goletto, Antonio Furnari, Siddhant Bansal, Francesco Ragusa, Giovanni Maria Farinella, Tatiana Tommasi







	Localisation and Navigation	12	
	Messaging	30	
	Action Recognition	213	
	Person Re-ID	24	
	Object Detection and Retriev	/al 🔽	
	Measuring System	89	
	Decision Making	9	
	3D Scene Understanding	10	
	Hand-Object Interaction	12	
	Summarisation	13	
	Privacy	14	
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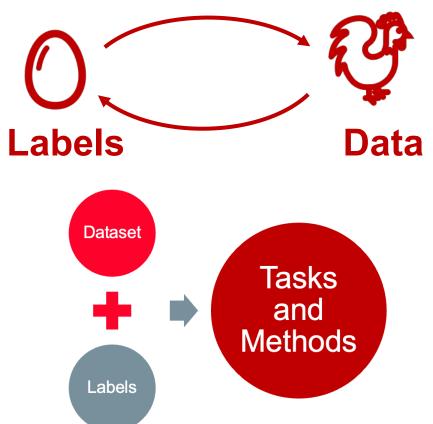




- 12 tasks
- 46 pages (excluding references)
- 462 references



In this talk...







Thank you

For further info, datasets, code, publications...

http://dimadamen.github.io



@dimadamen



http://www.linkedin.com/in/dimadamen



